Instruction Manual

B-H Analyzer SY-8218 / SY-8219



IWATSU ELECTRIC CO., LTD.

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Introduction

- ♦ Thank you for purchasing this IWATSU and please regularly use IWATSU lastingly in future.
- ◇ Please read this manual before using this product, then keep the manual handy for future reference.
- ♦ This instruction manual describes operating precautions, operating procedure, operation examples, and specifications.
- ♦ In this manual, it explains based on SY-8218. Especially as long as it doesn't refuse, please handle SY-8219 based on it.

Safety Precautions

To ensure safe operation of this product and to prevent injury to the user or damage to property, read and carefully observe the warnings \triangle and cautions \triangle in the following sections

Definition of warnings \triangle and cautions \triangle used in this manual

Warnings	Incorrect operation or failure to observe the warning may result in death or serious injury.
Cautions	Incorrect operation or failure to observe the caution may result in injury or damage to the instrument.

Notes

- ◇ Parts of the contents of this manual may be modified without notice for improvements in specifications and functions.
- Reproduction or reprinting of the contents of this manual without prior permission from IWATSU is prohibited.
- ♦ If any question about this product arises, contact lwatsu at the address listed at the end of this manual or our sales distributors.
- ♦ Utilities screen of this product shows settings of LAN and GPIB, and remote control option is required to operate the functions.
- \diamond For options written in this manual, contact our Web homepage or our sales personnel.

History

- ♦ May 2011: 1st edition
- ♦ November 2011: 2nd edition
- ♦ May 2012: 3rd edition
- ♦ July 2013: 4th edition
- ♦ January 2014: 5th edition
- ♦ July 2015: 6th edition
- ♦ September 2015: 7th edition
- ♦ May 2016: 8th edition
- ♦ Aug 2016: 10th edition
- ♦ Jun 2017: 11th edition

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• Do not touch the measurement POD terminal during excitation.

Touching it during excitation may result in an electric shock.

During measurement, put the POD cover on the POD.

This product may be used in combination with an external power amplifier (optional). The maximum voltage and current of the exciting power amplifier may be applied to the POD terminal which is connected to a sample.

To prevent danger, put the provided POD cover on the POD before starting measurement. If it is detected that the POD cover is not mounted, the supply of the exciting current is immediately shut down to stop the power supplied to the sample.



Marnings (Continued)

 If you notice smoke, foul odor or abnormal noise, immediately power off this product and remove the power plug from the receptacle.

Continued use under these circumstances may result in an electric shock or fire. Set the power switch on the front to STANDBY, turn off the main switch on the rear, and remove the power plug from the receptacle, and then contact lwatsu office or our sales distributors for repair. Do not attempt to repair this product yourself.

• Make sure no water gets on or inside this product.

Do not use this product if wet, otherwise an electric shock or fire could occur. If water gets on or inside this product, set the power switch on the front to STANDBY, turn off the main switch on the rear, and remove the power plug from the receptacle, and then contact lwatsu office or our sales distributors for repair.

• Do not place this product on an unstable support such as shaky base or inclined plane.

Dropping or falling-down of this product could result in an electric shock, injury, or fire. If this product is dropped or its cover is broken, set the power switch on the front to STANDBY, turn off the main switch on the rear, and remove the power plug from the receptacle, and then contact lwatsu office or our sales distributors for repair.

• Do not expose this product to excessive vibration or shock.

Dropping of falling-down of this product could result in injury.

• Dropping of this product could result in injury to your body or damage to your property.

When carrying this product, remove the measurement POD and cables and hold it by grasping the center of the handle in two places with both hands firmly so that it should not drop.

• Use 3-core power cord.

If not, an electric shock or fire may occur.

- If power is supplied from the 2-wire receptacle using the 3-core/2-core conversion adapter, connect the ground terminal of the 3-core/2-core conversion adapter to the ground.
- If power is supplied from the 3-wire receptacle using the provided 3-core power cord, grounding is made by the ground line of the power cord.

Warnings (Continued)

Always use this product with a specified power supply voltage.

If not, an electric shock, fire, or failure may occur. The range of operating voltage to be used is stated on the rear panel.

This product runs on AC power supply of single-phase, 50/60Hz and AC100-240V. No voltage selection is required, since this product automatically adapts to the power supply voltage.

Strictly observe items below when handling the power cord.

If not, an electric shock or fire may occur. If the power cord is damaged, contact lwatsu office or our sales distributors for repair.

- Do not modify the power cord. Do not pull the power cord.
- Do not forcibly bend the power cord. Do not heat the power cord.
- Do not twist the power cord. Do not let the power cord get wet.
- Do not bundle the power cord. Do not put heavy objects on the power cord.
- Do not touch the plug of the power cord with wet hands.

If not, an electric shock may occur.

• Do not make metal touch the blade of the power plug.

If not, an electric shock or fire may occur.

- Do not plug too many leads into a single receptacle. If not, a fire or overheating may occur.
- If thunder sounds, remove the power plug of this product from the receptacle and do not use it.

If not, a fire or electric shock may occur.

Do not remove the operation panel.

Since a high-voltage part exists inside, touching it may result in an electric shock. When inspecting or calibrating this product, contact lwatsu office or our sales distributors.



Do not modify this product.

Modification of it could result in an electric shock, fire, or failure.

In this product, the open security seal (Refer to the drawing for X page and "Repair and return of repaired product") is pasted to main unit and measurement POD. It is not possible to respond to the repair when the open security seal is peeled off, and remodeled.

Do not use this product when being failed.

If not, an electric shock or fire may occur. For a failure, contact lwatsu office or our sales distributors for repair.

• Do not put any metallic material or inflammable object through the ventilation port.

If any foreign object is put through the ventilation port, an electric shock, fire, or failure may occur. If any foreign object enters this product, set the power switch on the front to STANDBY, turn off the main switch on the rear, and remove the power plug from the receptacle, and then contact lwatsu office or our sales distributors for repair.

Do not put any object near to the exhaust port or ventilation port of this product.

If not, heat accumulates inside this product, causing an electric shock, fire, or failure.

• Before inserting the power plug into the receptacle, confirm no dust attached to it. In addition, remove the power plug and adapter from the receptacle and inspect/clean them once a half year or a year.

Dust may cause an electric shock, fire, or failure.



Read the following safety information.



Checking packed materials

When receiving this product, check the packed materials referring to components below (for the open bale chart, see the next page). If there is a lacked item or an item damaged during transportation, immediately contact lwatsu office or our sales distributors.

Components

B-H Analyzer main unit1
Standard Measurement POD1
Accessories
Power cord1
Cord strap1
POD cover1
AC couple module1
Power amplifier cable (BNC-BNC)1
OSC cable (BNC-SMA)1
Standard sample (TYPE A)1
Instruction manual (CD)1
User's guide1

[Information]

In our inspection process, rubbing that has adhered to the heaven side and the bottom of measurement POD cannot evade constructional.

There must not be influence on the performance, and please agree and put it.

Open bale chart (main unit and accessories)



Management of product

When disposing of this product, it is necessary to recycle or dispose of it properly in accordance with a local law or regulation. When disposing of it, request a recycle company to dispose of it in accordance with a local law or regulation

Repair and sending of repaired product

If a failure occurs, return this product to our service center. Any failure which occurs in the term of guarantee and for which lwatsu is responsible should be repaired without any cost.

When sending a product to be repaired, clearly write the product name, serial number (in the label on the rear of this product), and description of the failure, name, division, and telephone number of responsible person.

About the open security seal

In this product, the open security seal is pasted to main unit (one place) and measurement POD (two places) as shown in the figure below. In this product, the open security seal is pasted to main unit (one place) and measurement POD (two places) as shown in the figure below. Please note not responding to the repair when the open security seal is removed.



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Contacts

Chapter 1 Before Getting Start

■ 1.1 Features

• This product is this product to measure various types of physical amount of soft magnetic materials. It is equipped with the signal generator which can generate both a sine wave and a square wave, excites a sample while automatically increasing a magnetic field value or a magnetic flux density value gradually until they reach a specified value. When the value is reached, it starts measurement. In addition, not to leave any residual magnetization in a sample after measurement, it reduces magnetization by automatically applying an attenuation alternating magnetic field.

This product has also features below:

- By reviewing a sample for a calibration standard, it can make more accurate and more stable measurement than the lwatsu existing product for core loss and the like
- Since the number of pieces of obtained waveform data is 8,192 points/ cycle; i.e. 16 times as many as the lwatsu existing product, it can measure coercive force, residual magnetic flux density and the like with high accuracy.
- It can execute not only sine wave excitation but also pulse excitation (max.: 1 MHz, Duty 50 %, symmetry).
- Because of Reference function installed, it can compare B-H hysteresis loops which are measured under two different measurement conditions.
- Because of two types of cursor measurement functions (Cross and Grad) installed, it can display a measurement value and permeability at an arbitrary point
- Measurement data and measurement conditions can be stored in the CSV format with punctuation using tabs and screen hard copy can be stored in a USB memory in JPEG or PNG format.
- Measurement data and measurement conditions stored in a USB memory can be recalled to draw the stored data again and to make settings.
- It has the function to storage setting conditions before powering off and when it starts next time, it uses them.

■ 1.2 Cautions for installation

- Use this product within a specified range of temperature and humidity. If exposed to direct sunlight or used outside an operating range; e.g. high humidity, it may fail. Ranges of temperature and humidity for usage are as follows:
- Only indoor use
- Temperature: +5 °C to +35 °C (operation guaranteed range)
- Humidity: 85 % RH (+35 °C, non-condensation, operation guaranteed range)
- Do not place this product in a location with excessive moisture or dust. Otherwise, electric shock or fire may occur.
- Do not place an object on this product. If an object is placed on this product, the cover may contact the internal circuit, resulting in electric shock, fire, or failure.
- Do not place an object near to the exhaust port or ventilation port of this product. Otherwise, heat may accumulate inside this product, resulting in electric shock, fire, or failure.
- If this product falls, its impact may cause your body or property to be damaged. When carrying it, remove the measurement POD and cables and hold it by grasping the handle in two places at the center with both hands securely so that it does not fall.

■ 1.3 Cautions for transportation

• When transporting this product, remove the measurement POD from the main unit and use the packing material attached at the time of purchase or equivalent.

The case where a failure or damage occurs when transporting this product with the measurement POD attached to the main unit **shall not be** guaranteed.

- Remove the measurement POD as follows:
 - ① Loose two clamp knobs on the front of the measurement POD by rotating them counterclockwise.
 - (2) Apply both hands on both sides of the measurement POD and pull the measurement POD to your side horizontally along the guide rails.
 * Never use excessive power to pull it; otherwise, the measurement POD or guide rails may be damaged.
- Installation of the measurement POD is done in the reverse procedure of removing it, as follows:
 - ① Apply both hands on both sides of the measurement POD and insert it in the POD installation opening of the main unit, and press it along the guide rails to the bottom.
 - * Never use excessive power to install it; otherwise, the measurement POD or guide rails may be damaged.
 - (2) Install the measurement POD by clockwise rotating two clamp knobs on the front



■ 1.4 About Windows Embedded

- This product uses **Windows Embedded Standard** as the operating system but it **is not disclosed to a customer**. If behaviors below cause a failure or damage, this product **shall not be guaranteed and repaired**.
- Never connect a keyboard or a mouse to the USB port of this product; i.e. operation is not guaranteed.
- Never connect other than a USB memory and options specified by Iwatsu to the USB port of this product; i.e. operation is not guaranteed.
- Never insert any customer's file in C or D drive of this product using an illegal method or never install your application software.

Chapter 2 Measurement Principle

■ 2.1 Basic measurement principle

• The basic measurement principle used by this product to obtain a magnetic field strength H and a magnetic flux density B generating in a sample to be measured is explained using the 2-coil method.

Fig.2-1 shows a measured sample to which the primary turns are applied for excitation (No. of turns: N_1) and the secondary turns are applied for detecting the magnetic flux density (No. of turns: N_2). Fig.2-2 shows the diagram outlining a measured sample connected to this product using the optional power amplifier.

The signal generator built in this product generates an excitation signal and the power amplifier amplifies the signal, allowing the exciting current $i_1(t)$ to flow through the primary turns.

The exciting signal i_1 (t) is converted into a voltage Vs (t) by the shunt resistor with a resistance value of Rs built in this product.







Therefore, the magnetic field strength H (t) generating in the measured sample can be obtained using:

$$H(t) = \frac{N_1 \cdot i_1(t)}{L_e} = \frac{N_1 \cdot V_s(t)}{L_e \cdot R_s}$$
(2.1)

An induced voltage V_2 (t) is also generated between both sides of the secondary turns. Therefore, the magnetic flux density B (t) in the measured sample can be obtained using:

$$B(t) = \frac{1}{N_2 \cdot A_e} \int_0^t V_2(\tau) d\tau \qquad (2.2)$$

■ 2.2 Expressions to calculate measurement values

• The following is explanation of expressions to calculate values measured by this product.

This product uses two measurement modes of Normal mode and μ mode, and Table 2-1 shows measurement values displayed in each calculation mode.

The calculation difference point of Normal mode and µ mode is the following. In µ mode, the complex permeability from fundamental wave element of intensity of the magnetic field H and magnetic flux density B is calculated. In Normal mode, the value which is not calculated by using them is calculated. Refer to the following expressions for details

jare typical. The symbol to which adheres is calculated from the fundamental wave element.							
Calculation		Norm	nal mode	µ mode			
modes	Symbol	Typical unit	Meaning	Symbol	Typical unit	Meaning	
	Pcv	[W/m ³]	Core loss per volume	Bm	П	Max. magnetic flux density	
	Pcm	[W/kg]	Core loss per mass	V ₂ m	M	Max. induced voltage	
	θ	[deg]	Phase angle	Hm	[A/m]	Max. magnetic field	
	μ _a	—	Relative permeability	l₁m	[A]	Max. exciting current	
	Bm	П	Max. magnetic flux density	μ _a	—	Relative permeability	
	V ₂ m	M	Max. induced voltage	*L	[H]	Inductance	
alues	Br	П	Residual magnetic flux density	*R	[Ω]	Resistance	
ent va	Hm	[A/m]	Max. magnetic field	* Z	[Ω]	Impedance	
eme	Hc	[A/m]	Coercive force	Pc	[W]	Core loss	
leasu	Pc	[VV]	Core loss	* μ'	_	Complex permeability (real part)	
2	VA	[VA]	Apparent power	* µ″	—	Complex permeability (imaginary part)	
	l₁m	[A]	Max. exciting current	*µz	_	Impedance permeability	
	Br/Bm	—	Rectangular ratio	* 0	[deg]	Phase angle	
	2Фm	[Wb]	Total flux linkage	*Q	—	Quality coefficient	
	_	—	_	*tanδ	—	Loss coefficient	
	_	-	_	THD	[dB]	Total harmonic distortion	

Table 2-1 Calculation modes and measurement values
--

* Units in [] are typical. The symbol to which * adheres is calculated from the fundamental wave element.

Expressions used by this product to calculate each value shown in Table 2-1 are as follows:

Hm, Hc, Bm, Br, μa, Br/Bm, 2Φm For symbols, see Figure 2-3.

$$H_{m} = \frac{\left|H_{m}\uparrow\right| + \left|H_{m}\downarrow\right|}{2} \tag{2.3}$$

$$B_m = \frac{\left|B_m \uparrow\right| + \left|B_m \downarrow\right|}{2} \tag{2.4}$$

$$H_{c} = \frac{\left|H_{c}\uparrow\right| + \left|H_{c}\downarrow\right|}{2} \tag{2.5}$$

$$B_r = \frac{\left|B_r \uparrow\right| + \left|B_r \downarrow\right|}{2} \tag{2.6}$$



$$\mu_a = \frac{B_m}{\mu_0 H_m} \tag{2.7}$$

(μ_0 : Vacuum permeability $4\pi \times 10^{-7}$ [H/m])

$$B_r / B_m = \frac{B_r}{B_m}$$
(2.8)

$$2\phi_m = A_e \left(B_m \uparrow - B_m \downarrow \right) \tag{2.9}$$

$$P_{c} = \frac{N_{1}}{N_{2}} \cdot \frac{1}{T} \cdot \int_{0}^{T} i_{1}(t) \cdot V_{2}(t) dt$$
 (2.10)

$$P_{cv} = \frac{P_c}{V_e}$$
(2.11)

$$P_{cm} = \frac{P_c}{W_e}$$
(2.12)

$$VA = \frac{N_{1}}{N_{2}} \cdot i_{1RMS}(t) \cdot V_{2RMS}(t)$$
(2.13)

(RMS: Effective value)

Normal mode

$$\theta = \cos^{-1} \left(\frac{P_c}{VA} \right) \tag{2.14}$$

* The θ of μ mode is calculated by the expression (2.17).

$$\mu = \mu' - j \,\mu'' = \frac{B(\omega_0)}{\mu_0 \,H(\omega_0)}$$
(2.15)

(µ: Complex permeability, j: imaginary unit, $\omega_0=2\pi f_0$, f_0: measurement frequency)

$$\mu_z = \sqrt{(\mu')^2 + (\mu'')^2}$$
(2.16)

 μ mode

$$\theta = \cos^{-1} \left\{ \frac{P_c(\omega_0)}{VA(\omega_0)} \right\}$$
(2.17)

$$Q = \frac{\mu'}{\mu''} \tag{2.18}$$

$$\tan \delta = \frac{1}{Q} \tag{2.19}$$

$$L = \frac{\mu' \,\mu_0 \,A_e \,N_1^2}{L_e} \tag{2.20}$$

$$R = \frac{\omega_0 \ \mu'' \ \mu_0 \ A_e \ N_1^2}{L_e}$$
(2.21)

$$|Z| = \sqrt{R^2 + (\omega_0 L)^2}$$
 (2.22)

$$THD = 20\log_{10}\frac{\sqrt{V_2^2(3\omega_0) + V_2^2(5\omega_0) + V_2^2(7\omega_0)}}{V_2(\omega_0)}$$
(2.23)

Chapter 3 Names and Functions of Each Part

■ 3.1 Front panel



■ 3.2 Rear panel



■ 3.3 Operation panel

• Functions of the operation panel are as follows:

ENTRY area



■ 3.3.1 ENTRY area

[Ten keys]



- It displays number keys (0 9), character keys (upper, lower cases), symbols (., -, #), space.
- For a key on which several characters are written, a displayed character changes each time it is pressed.

7 PQRS [Ex.]

Each time pressed, a displayed character changes as follows:

 $7 \mathop{\rightarrow} P \mathop{\rightarrow} Q \mathop{\rightarrow} R \mathop{\rightarrow} S \mathop{\rightarrow} p \mathop{\rightarrow} q \mathop{\rightarrow} r \mathop{\rightarrow} s \mathop{\rightarrow} 7 \mathop{\rightarrow} P \dots$

* On Edit box into which only numeric value can be entered, characters, -, #, and space cannot be displayed.
* -/ # key changes only among -, #, and space.

[ENTER key]



- Popup Edit Box:
- It determines an alphanumeric character to be entered in the box.
 - Popup List:: It determines an item to be selected from the list.
 - Measurement screen: It determines a position to be changed and allows the position to pop up.

[EXIT key]

- EXIT
- It closes Popup Edit Box and Popup List.
- It closes Utilities screen and Configuration screen.
 - If Popup Edit Box is closed during input operation, the settings just before closing should be kept.

[Arrow keys]



• On Popup Edit Box input:



The edition cursor moves to the **right** by one character.



The edition cursor moves to the left by one character.



A current character displayed on the edition cursor changes as follow: Character: $A \rightarrow B \dots Y \rightarrow Z \rightarrow a \rightarrow b \dots y \rightarrow z \rightarrow A \dots$

Number: $1 \rightarrow 2 \dots 9 \rightarrow 0 \rightarrow 1 \dots$

A current character displayed on the edition cursor changes as follow: Character: $A \rightarrow z \dots b \rightarrow a \rightarrow Z \rightarrow Y \dots B \rightarrow A \dots$

Number: $1 \rightarrow 0 \dots 3 \rightarrow 2 \rightarrow 1 \dots$

• On Popup List display:



The edition cursor moves downward by one line.

• On measurement screen, Utilities screen, Configuration screen: The edition cursor moves in the direction of the key.

[Function knob]



• On Popup Edit Box: Clockwise rotation allows a current character displayed on the edition cursor to change as follows: Character: $A \rightarrow B \dots Y \rightarrow Z \rightarrow a \rightarrow b \dots y \rightarrow z \rightarrow A \dots$ Number: $1 \rightarrow 2 \dots 9 \rightarrow 0 \rightarrow 1 \dots$ Counterclockwise rotation allows a current character displayed on the edition cursor to change as follows: Character: $A \rightarrow z \dots b \rightarrow a \rightarrow Z \rightarrow Y \dots B \rightarrow A \dots$ Number: $1 \rightarrow 0 \dots 3 \rightarrow 2 \rightarrow 1 \dots$ On Popup List: Clockwise rotation allows the edition cursor to move downward. Counterclockwise rotation allows the edition cursor to move upward. On measurement screen, Utilities screen, Configuration screen: The edition cursor moves (For details on the cursor below. see "6.7 Cursor measurement") • Cursor display (B-H graph): Clockwise rotation allows the cursor to move in the direction of time going forward. Counterclockwise rotation allows the cursor to move in the direction of time going backward • Grad cursor display (B-H graph): Clockwise rotation allows the cursor to move clockwise. Counterclockwise rotation allows the cursor to move counterclockwise. Vertical cursor display (time axis graph): Clockwise rotation allows the cursor to move to the right. Counterclockwise rotation allows the cursor to move to the left. · Cursor display: Pressing it allows cursor movement to toggle between Coarse (unit of 20points) and Fine.

[CLEAR key]



- Popup Edit Box allowing character input
- : It clears characters in the box.
- Popup Edit Box allowing only number input
- : It sets a number in the box to 0.

[CANCEL/ UNDO key]



- Edit Box selection : Pressing it allows items in the box to toggle between old settings/ current settings.
- Popup Edit Box input : It cancels an entry and closes Popup Edit Box.
 - List Box selection : Pressing it allows items in the box to toggle between old settings/ current settings.
 - : It cancels a selected item and closes Popup List. Popup List display
 - * When a Reference measurement value appears, UNDO does not function.

■ 3.3.2 SYSTEM area

[SAVE/RECALL key]



- Selection of SAVE/RECALL allows Popup List to appear.
- If pressed when Popup List is displayed, Popup List is closed.

[UTILITIES key]



- · It displays Utilities screen.
- If pressed when Utilities screen is displayed, the screen is closed.
- * The screen can also be closed by pressing EXIT key.

■ 3.3.3 MEASUREMENT area

[START key]



It starts measurement.

[STOP key]



If pressed during measurement, the measurement is forcibly stopped.

[MODE key]



- It displays Popup List to select a measurement mode.
- · If pressed when Popup List appears, the list is closed.

[CONFIG key]



- It displays Configuration screen.
- If pressed when Configuration screen appears, the screen is closed.
 - * The screen can also be closed by pressing EXIT key.

[STORAGE key]



- It memorizes Current waveform displayed in yellow after measurement as Ref. (Reference) waveform.
- * If there has already been Reference waveform, it is overwritten.

■ 3.3.4 DISPLAY area

[VIEW MODE key]



• Each time pressed in a measurement screen, a displayed graph is changed to a time axis graph/ B-H graph.

[CURSOR key]



- It displays Popup List to select a measurement cursor.
- If pressed when Popup List appears, the edition cursor moves **downward**. If this state is kept for approx. 3 seconds, selection of an item on the edition cursor is determined and Popup List closes automatically.

[PRINT key]



- A copy on the measurement screen is generated to a specified output destination in a specified file format.
- * The file format and output destination are specified in Print frame on Utilities screen (for details, see "= 5.3 Setting of Print").

[SELECT key]



• If Reference waveform is memorized on the measurement screen, each press of it allows Current/ Ref. waveforms to be displayed or not as follows: (For details, see "
6.9 Reference function".)

Table 3-1 Function of SELECT key

[Explanatory note] ●: display —: not display

Operation	Display graph		Cursor measuring object		Meas. condition		Meas. value	
	Current	Ref.	Current	Ref.	Current	Ref.	Current	Ref.
1		—		—		_		—
Press once based on $\textcircled{1}$	—				—	•	_	•
Press twice based on $\textcircled{1}$				—		-		—
Press 3 times based on $\textcircled{1}$			_		—	•	—	
Press 4 times based on $\textcircled{1}$	Same as ①		Same as ①		Same as ①		Same as ①	
Repeated same as above								

Chapter 4 Preparation Before Operation

■ 4.1 Flow before measurement

• The flowchart below shows procedures before measurement.



D: Outer diameter

d: Inner diameter

P Density h Height

2

Le: Effective length of

magnetic path Ae: Effective net core area

■ 4.2 Calculation of sample constants

• If a sample constant required for measurement is not attached to the sample, use the following calculation expression to obtain an approximate constant. For details, see JIS standard and the like.

Cross section

D

d

A e

Toroidal core

For a toroidal core with the shape shown in Fig.4-2, use the following calculation expression to obtain the sample constant:

 $A_e \cong \frac{(D-d)h}{2}$

 $V_e \cong L_e \cdot A_e$

 $W_e \cong \rho \cdot V_e$

Effective length of magnetic path: L

$$u_e \cong \frac{\pi \left(d+D\right)}{2}$$
 (4.1)

(4.2)

(4.3)

(4.4)

Effective net core area:

Effective volume:

Mass:



For an El core with the shape shown in Fig.4-3, use the calculation expression to obtain the sample constant:

Effective length of magnetic path: $L_e \cong a + 2b - c - \frac{d}{2} - e + f$ (4.5)

Effective net core area: $A_e \cong d \cdot h$ (4.6)

Effective volume: $V_e \cong L_e \cdot A_e$ (4.7)

Mass:

$$W_e \cong \rho \cdot V_e \tag{4.8}$$



4.3 Calculation of gain and current necessary for power amplifier

- When using a power amplifier, its gain and current should be predicted in advance. The procedure is described below.
 - * The explanation below is written assuming that a waveform to be observed is an ideal sine wave or an ideal symmetry square wave with Duty of 50%. Under a measurement condition which is not in this ideal state because of characteristics of a sample, the obtained gain below should be used as a standard.

Prediction of gain by using Max. magnetic flux density Bm

The following is the procedure to predict a gain necessary for a power amplifier using Max. magnetic flux density Bm generated in a sample.



① Define the measurement frequency f and the Max. magnetic flux density Bm to be generated in the sample, and then obtain Max. induced voltage V₂m using expression (4.9) if the excitation signal is a sine waveform or using expression (4.10) if it is a symmetry square waveform with Duty of 50%.

For excitation signal of sine wave:	$V_{2m} = 2\pi f N_2 B_m A_e$	(4.9)
For excitation signal of symmetry square	$V_{2m} = 4 f N_2 B_m A_e$	(4.10)
waveform with Duty of 50%:		

If V₂m exceeds 200[V], this product cannot make measurement; i.e. Maximum measurement induced voltage of this product is 200[V].

Never enter any voltage exceeding 200[V] in this product. Otherwise, it may fail. Moreover, do not use the power amplifier exceeding the rated power. Otherwise, it may fail.

② Next, obtain the maximum exciting voltage V₁m which is obtained by converting Max. induced voltage V₂m into the primary turns side, using expression (4.11). It can be applied independent of a type of the exciting signal.

$$V_{1m} = \frac{N_1}{N_2} \cdot V_{2m}$$
(4.11)

If V₁m exceeds the maximum output voltage of the power amplifier to be used, it is considered that any measurement cannot be made under this condition. Originally at this step, in consideration of the voltage descent of the shunt resistance, the current that flows to the primary side of the sample is not predictable. Moreover, the voltage descent of this shunt resistance is not considered because it is small.

③ Using results above, obtain the gain G required for the power amplifier using the maximum signal output voltage V₀m=2.8[V₀P] of this product and expression (4.12).

$$G = \frac{V_{1m}}{V_{0m}} \cdot \tag{4.12}$$

④ Set the power amplifier to a value which exceeds the obtained gain G and is the lowest in the settable gains.

Prediction of current by using Max. magnetic field Hm

The following is the procedure to predict the current necessary for a power amplifier using Max. magnetic field Hm to be applied to a sample. It can be set independent of a type of an exciting signal.

① Define Max. magnetic field Hm to be applied to a sample and then obtain Max. exciting current i₁m (i₁m is the same as I₁m in Section ■ 4.4 Turns of a sample or later) using expression (4.13).

$$i_{1m} = \frac{L_e H_m}{N_1}$$
 (4.13)

If in exceeds 6.0[A], this product cannot make measurement. In addition, if the maximum output current of a power amplifier used is exceeded, it is considered that measurement cannot be made under this condition.

Never enter any current exceeding 6[A] in this product. Otherwise, it may fail. Moreover, do not use the power amplifier exceeding the rated current. Otherwise, it may fail.

■ 4.4 Turns of a sample

• The following is the example of applying turns to a sample.

No. of turns

No. of turns is the important factor deciding Max. magnetic field Hm and Max. magnetic flux density Bm. Basically, Iwatsu recommends that:

- No. of primary turns N₁ should be 3 turns or more, No. of secondary turns N₂ should be 1 turns or more, and N₁ is equal to N₂ as much as possible.
- No. of turns should be determined considering above and referring to Section 4.3 while taking notice of below:
- ① Necessary Hm and Bm are obtained and V₂m does not exceed 200[V]. I₁m does not exceed 6[A]. In addition. if a power amplifier is used, V₁m and I₁m do not exceed the maximum output of the power amplifier.
- (2) To avoid resonance caused by a sample and the input capacitance of this product when making measurement with a measurement frequency f [Hz], the inductance L [H] of the sample to which turns is applied should satisfy expression (4.14).

$$L \le \frac{1}{\left(20\,\pi\,f\,\frac{N_2}{N_1}\right)^2 20 \times 10^{-12}} \tag{4.14}$$

* L should be obtained by inductance measurement.

How to apply turns

If No. of primary turns N_1 is equal to No. of secondary turns N_2 , the bifilar winding shown in Fig. 4-5 is recommended. It is made by making a twisted pair using primary and secondary lines and winding the pair onto the core.

The magnetic flux for the bifilar winding leaks less than when primary and secondary lines are wound individually: i.e. coupling coefficient between primary and secondary turns can be improved.

When make winding, take notice of below. Influence by leaked magnetic flux and eddy current can be reduced.

- When applying winding, adhere line material to a sample as close as possible.
- Intervals between turns are as equal as possible.
- Twisted pair interval between primary and secondary lines is as close as possible.
- The thickness of material of a winding line is as thin as possible within the range permitted by a maximum current used.

Termination processing of windings

Knots should be made at both ends of primary and secondary lines as marks as shown in Fig. 4-6 so that wrong connection to the measurement POD is reduced.





Fig.4-5 Bifilar winding

■ 4.5 Connection of equipments

- The following shows how to connect equipments necessary for measurement.
- Connecting the main unit and the measurement POD.

The following is the procedure to connect the measurement POD to the main unit.

- ① Insert the measurement POD into the opening on the front of the main unit and press it into the bottom.
- ② Fix the measurement POD by clockwise rotating two clamp knobs on the measurement POD simultaneously. (See 1.3 Cautions for transportation" and Fig.1-1.)



When installing, removing, or replacing POD, make sure to **turn off POWER switch on the front panel of this product;** i.e. nothing appears on LCD screen.

Otherwise, this product may fail.

Connecting the power amplifier

The following is the procedure to use a combination of the power amplifier and this product.

- ① Connect OSC OUTPUT at the lower right on the front panel of the main unit with INPUT of the power amplifier using the provided OSC cable (BNC-SMA).
- * Connect them with an optional OSC cable for SY-911 and IE-1125 when the power amplifier is IE-1125 or IE-1125x.
- ② Connect OUTPUT of the power amplifier with POWER INPUT at the left on the measurement POD using the provided power amplifier cable (BNC-BNC).
 - If a power amplifier is not used, connect OSC OUTPUT at the lower right on the front of the main unit with POWER INPUT at the left of the measurement POD using the provided OSC cable (BNC-SMA).





Before making connection, **make sure to read** the instruction manual of the power amplifier to be used. If reverse connection is made for input/ output of the power amplifier or this product, **fatal damage to this product or the power amplifier** may be caused.

■ 4.6 Connection of sample

• A sample is connected to the measurement POD as follows:

2-coil method

- ① Connect the start of the primary turns to P2 terminal and the end to P1 terminal.
- ② Connect the start of the secondary turns to S2 terminal and the end to S1 terminal.





1-coil method

If the secondary turns cannot be applied, measurement uses 1-coil method. In this case, Core loss Pc includes the copper loss of the primary turns, therefore Pcv, Pcm, and θ include its influence. In addition, make sure to select 1-coil method in Configuration for measurement.

(For settings, see "5.4 Measuring Method".)

- ① Connect the start of turns to P2 terminal and the end to P1 terminal.
- 2 Short-circuit P2 and S2 terminals.
- 3 Short-circuit P1 and S1 terminals.



Fig.4-9 1-coil method

* It is recmmended that Fixed Parameter by 1-coil method is set in 11m and Hm specification.

Because the secondary turns is not given as for 1-coil method, induced voltage $V_2(t)$ in the basic measurement principle chart of Fig.2-2 will directly measure the voltage between the primary turns. In this case, it differs from 2-coil method, and voltage drop in shunt resistance R_s by exciting current $i_1(t)$ and equivalent series resistance R_L of sample will be superimposed to $V_2(t)$.

Therefore, the measurement might not go well because of the superimposition when I1m or Hm is specified for the target parameter. Especially, voltage drop in shunt resistance R_s and equivalent series resistance R_L grows when exciting current $i_1(t)$ grows, and, in addition, the measurement doesn't go well.

■ 4.7 Powering on and off

- The following is method to power on/ off this product
- Powering on
- ① Turn on the main power switch on the rear of this product.
 * Advance to following ② after you wait for a few seconds after the main power source is turned on.
 Error E08 occurs if not neatly waiting.
- (2) Turn on POWER switch by pressing it at the lower left of the front panel.
 - Press POWER switch in the state where a USB memory is not inserted. If not, this product may not start.



Fig.4-10 Main power switch on the rear

- ③ After Windows desktop screen appears for a while on the LCD screen of this product, the start progress bar screen appears for approx. 1 min, the bar disappears and then this product is ready to operate.
 - * When the progress bar appears after turning on POWER switch, never press POWER switch at the lower left of the panel. Otherwise, this product may malfunction.
- (4) Before starting measurement, warm up this product 30 minutes or more after the progress bar disappears (in (3)).
 - * For warming up of a power amplifier, refer to the instruction manual of it.

Caution!

Explanatory note that a low frequency sound may be generated when turning on the switch on the rear. It does not affect characteristics and life of this product at all, because it is caused by a low frequency vibration in transition of a choke coil for high-frequency measures.

Powering off

- ① Press POWER switch at the lower left on the front panel of this product. The screen changes to blue and after **approx.30 seconds**, this product is powered off.
- ② After nothing appears on LCD screen, turn off the main power switch on the rear.
 - * Turn off the power supply of the power amplifier after turning off the power supply of this product when you use the power amplifier.

Memorizing measurement conditions

① When powering on again, the measurement screen in the measurement mode just before previous powering off is displayed and measurement conditions at that time are used.
Chapter 5 Setting Before Measurement

■ 5.1 Setting of Unit

UTILITIES

- It sets the units of a measurement value and a sample constant.
 - Press

to display Utilities screen (see Fig.5-1).

2 Move the edition cursor to the measurement value whose unit is to be

changed or List Box of the sample constant and press

3 Popup List opens. Move the edition cursor to the Selectable unit and press



④ Press

UTILITIES

Table 5-1 explains each symbol and shows units to be selected.

to close Utilities screen. or

EXIT

* If the other item is to be changed, Utilities screen need not be closed.



Fig.5-1 Utilities screen

[Explanatory note] Bold: Factory settings					
Symbol (description)	Selectable unit	Symbol (description)	Selectable unit	Symbol (description)	Selectable unit
Le	mm	Freq.	Hz	Dom	W/kg
(Effective length of	cm	(Measurement	kHz		W/g
magnetic path)	m	frequency)	MHz	(Core loss per mass)	mW/g
Ae (Effective net core area)	μm ² mm ² cm ² m ²	B (Magnetic flux density)	mT T	L (Inductance)	μH mH H
Ve (Effective volume)	mm ³ cm ³ m ³	Pc (Core loss)	mW W	I₁m (Exciting current)	mA A
We (Net volume)	g kg	Pcv (Core loss per volume)	W/m ³ kW/m³ mW/cm ³	V₂m (Induced voltage)	mV V

Table 5-1 Setting of units

ENTER

■ 5.2 Setting of Information

 It sets the information to be generated from this product.
① Press to display Utilities screen (see Fig.5-1).
② Move the edition cursor to List Box of the output information whose Information is to be changed and press
③ If Popup List opens, move the edition cursor to the item to be set and press to determine the setting.
 If Popup Edit Box opens, use ten keys to enter a number and press And press Or, rotate To change a number and press To determine the setting.
Table 5-2 shows description of each output information and selectable items.
S Press or billities or billities screen.

Table 5-2 Setting of output information

[Explanatory note] Bold: Factory settings

Items	Selectable items	Description		
	On	Sound on	Selection of whether or not start sound of this product,	
Sound	ound Off Sound off	Sound off	measurement finish sound, operation sounds for operation panel and keys is generated.	
Morning	On	Message appears	Selection of whether or not an error message and warning	
warning	Off	No message	message is displayed on the screen.	
Date	—	Sets date of this product.		
Time		Set time of this product.		

■ 5.3 Setting of Print

• It sets the file format and output destination of a screen hardcopy



[Explanatory note] Bold: Factory settings

Items	Selectable items	Description	
File Format	jpg	jpg format	*510.00
	png	png format	Sets the format of a screen hardcopy.

* 5-1: The destination of the output of the screen hard copy is USB memory. When optional remote software SY-810 is used, the output destination becomes connected PC.

■ 5.4 Setting Measuring Method



Table 5-4 Setting of measurement method

[Explanatory note] Bold: Factory settings

Items	Selectable items	Description			
A. 101000	Power of 2 ⁰ - 2 ⁶	Selects No. of averaging times of measurement signal waveform *52 (1, 2, 4, 8, 16,			
Average	16	64)			
Doto /	Power of 2 ³ - 2 ⁵				
Reuy	8	Selects the upper limited No. of ti	mes of excitation until values of specified Fixed		
	Power of 2 ³ - 2 ⁵	Parameter (target parameter) co	nverge within Tolerance *5-3		
Maint Retry	Free	Maint Retry mode is used only for service and not disclosed to a customer.			
	8				
Mose Asse	Odd in 1 - 111	Selects the moving average num	ber applied to sample data of a measurement signal		
Mov-Avg 3 waveform *54.		waveform*5-4.			
Ceil	1	1-coil method	Selects 1-coil method or 2-coil method to		
Coil	2	2-coil method	measure a sample.		

- * 5-2: Increased number of times for averaging allows higher quality measurement. However, if the number of times for averaging is set too large, the measurement time may become long or temperature of a measured sample may rise depending on measured samples or measurement conditions, resulting in effect on a measurement value. Care should be taken.
- * 5-3: Normally, 8 are recommended for a default number of times. If the number is too large, the number of times for excitation increases which causes temperature of a sample to rise, resulting in damage to the sample.
- * 5-4: Increased number of times for moving average allows noise ingredients included in measurement signals to be reduced. However, if the number is too large, the original measurement signal may deteriorate.

■ 5.5 Setting of Equipment

- It sets the name of a power amplifier to be connected, the gain of the power amplifier, and the rise time of a pulse for pulse excitation.
 - ① Press

to display Configuration screen (see Fig.5-2).

2 Move the edition cursor to List Box of a measurement item for Setting of Equipment to be changed and press

③ When Popup List opens, move the edition cursor to the item to be set and press

ENTER

oress to

to determine the selection.

Table 5-5 shows description of each item and selectable items.

Press
 ONFIG
 or
 EXIT
 to close Configuration screen.

Table 5-5 Setting of Equipment

[Explanatory note] Bold: Factory settings

ltems	Selectable items		Description	
	IE-1125	Select a power amplifier name to connect. The power amplifier name is displayed of		
	IE-1125A	the measurement screen and saved when data is saved.		
	IE-1125B	1		
D	HSA4014-IW	• If Other is selected	d, Edit Box just under it can accept an entry; i.e. an arbitrary	
Power Amp	HSA4052-IW	amplifier name car	be entered (up to 10 characters)>	
	HSA4101-IW			
	Other			
	Not Used			
Devuer Arran Caire	Integral number 1 - 100	Selects a gain of a p	ower amplifier to connect. A gain is displayed on the measurement	
Power Amp Gain	10	screen and saved when data is saved .		
Pod	-	Displays the Pod name corresponding to the selected measurement mode.		
	Off	BW filter—Off	Selects an approximate rise time of a pulse signal generated for	
BW for Pulse	100ns	Approx. 100ns	pulse excitation. Setting to Off makes the rise time fastest.	
	200ns	Approx. 200ns		

Table 5-6 Options and measurement PODs corresponding to them

Chapter 6 Measurement

■ 6.1 Selecting measurement mode

- It selects a measurement mode.
 - ① Press **[11]** to display Mode menu (see Fig.6-1).
 - 2 While referring to Table 6-1, move the edition cursor to the mode to be used for measurement"6-1

and press

to determine the selection.

- (3) The screen of the selected measurement mode appears.
- Press or to close Mode menu screen.
 - * 6-1: This product recognizes connected measurement POD automatically. If measurement POD connected with the selected measurement mode is not corresponding, error E12 is displayed when the measurement begins. After the stop of the power supply, try to connect the correct POD again.

Table 6 1 Measurement	modes and displayor	d maasuramant POD namas
	modes and displayed	u measurement rod names

Measurement modes	Measurement POD names	Descriptions
Standard	SY-951	Standard measurement POD for SY-8218
Cont	SY-955	Standard measurement POD for SY-8219
Chamber	SY-320x/321x	Chamber Scanner System
Sheet	SY-956	Mini Single Sheet Tester
DC Bias	SY-960	DC Bias Tester



■ 6.2 Measurement screen

• The measurement screen is outlined.

	1 Sample Parameters			(2) Excited Conditions		
③ Mode	(4) Select	/	(5) Cursor Values	/	6 Measured Values	
	Sample Parame Sample Name : S Le : 83.878 m Ae : 2.04 m Mode STD	eters	m ³] N1 : 33] N2 : 33 les I :	Excited Conditions Function : Frequency : Hm : Tolerance : ± : Measured Values	Normal 0.05 [kHz] 130 [A/m] [%]	
	1 [mT]	/div Fine B	Н	Pcw : Pcm : θ : μa : Bm : V2m : Br : Hm : Hc : Pc : VA : I 1m :	[k W / m ³] [W / kg] [deg] [mT] [MT] [A/m] [A/m] [W] [VA] [A]	
	IWATTE	SY-8219 2015-0	1 [A/m] /div 01-27 10:46:35	Br/Bm: 2	[Wb] SC-OUT: × 0.2 Retry : 8	
	(7) Graph	Fia.6-2	Measurement scr	een (8) Configuratio	ons	

- ① Sample Parameters : Sets the sample name and the sample constant.
- 2 Excited Conditions : Sets the measurement condition.
- ③ Mode : Displays the current measurement mode.
- ④ Select : Indicates whether the currently displayed graph is Current (for current measurement) or Reference (for saved measurement).
- (5) Cursor Values : Displays the cursor value when the cursor appears.
- 6 Measured Value : Displays the measurement value.
- ⑦ **Graph**: Displays B-H graph or time axis graph.
- (8) **Configurations**: Displays main values being set in Configurations.

■ 6.3 Input of sample constant

ENTER

- The sample constant of a measured sample is entered.
 - ① While referring to Table 6-2, move the edition cursor to Edit Box of the sample constant to be entered on Sample Parameters

and press

to determine the selection.

2 When Popup Edit Box opens, while referring to "Input rules" in Table 6-2, use the ten key to enter alphanumeric characters



Table 6-2 Sample constant

Items	Input rules	Description	
Sample Name	Up to 20 characters		
Sample Name	None	Sample name	
	0.001 - 99999	Effective length of	
Le	10	magnetic path	
A a	0.001 - 99999	Effective not core area	
Ae	10	Ellective net core area	
	0.001 - 99999	Effective velume	
ve	100		
We	0.001 - 99999	Mass	
vve	1	IVIDSS	
N/4	0.1 - 9999.9	Drimon (turno	
	1	Filmary turns	
N2	0.1 - 9999.9	Secondary turns	
NZ	1	Secondally lums	

[Explanatory note] Bold: Factory settings

■ 6.4 Setting of measurement condition

• The measurement condition is set.

① While referring to Table 6-3, move the edition cursor to Edit Box of the measurement condition to be entered on Excited Conditions and



Table 6-3 Measurement condition

[Explanatory note] Bold: Factory settings

Items		Selectable items/ input rules				Description	
Function		Sine		Sine wave	Soloate a type of evoltation signal		
			Pulse		*6-2 Square wave	Selects a type of excitation signal.	
C.			Normal		Solocts calculation		
U.	aic.		μ		Selects calculation	mode.	
		SY-8218	10Hz to 2	10MHz			
	Sine wave	SY-8219	10Hz to	1MHz			
Frequency		100		Selects a frequency of excitation signal.			
	Square						
	wave						
		Bm (Max. magnetic flux density)					
Eivad D	romotor	Hm (Max. magnetic field)		0.001 to	*63 Selects and sets a target parameter va	acta a tarrat parameter valua for	
(Target p	arameter)	I1m (Max. excitation current)		99999		sets a target parameter value for	
(Targer p	arameter	V2m (Max. induced voltage)			measuremen	L	
		1					
			0.4.4000/		*6-3 Sets the tolerance X. The tolerance X is used for the		
			0.1~100%		criteria to finish	measurement; i.e. X [%] is the ratio of	
Iolei	Tolerance		_		an actual value	e to a target parameter setting value	
			1		and if X is reached, measurement finishes.		

* 6-2: µ mode cannot select a square wave. This product generates the symmetry square wave with Duty=50 %.

* 6-3: To understand the meaning of the target parameter and Tolerance, it is necessary to understand the measurement process of this product.

The measurement process of this product is explained referring to Fig.6-3 which indicates the measurement process specifying Max. magnetic field Hm as a target parameter, setting Tolerance=x [%], and using the horizontal axis as time.



When measurement starts, this product gradually increases the signal output and excites a sample while observing a peak value of the magnetic field H.

And then, when H exceeds a specified setting value Hm, this product makes the 1st measurement while keeping the excitation status. The period after starting the excitation until H exceeds Hm is called an **approx. value excitation period**.

If H obtained in the 1st measurement is within the range of $H_m \pm \frac{x \cdot H_m}{100}$, the measurement finishes at that time,

magnetization is reduced from the sample so that any residual magnetization is not left, and the measured value is displayed. If H is not within the range, the signal output is changed so that H can approach to Hm while exciting the sample.

In this period, the 2nd measurement is made and the same processing as the 1st measurement is done. This period is called **Gradual approach excitation period**.

That is, until the specified value of the target parameter become within the setting Tolerance, this product repeats measurement while changing the signal output.

The upper limit number of retries is set by Retry on Configuration screen.

If a measurement result is not within a setting Tolerance after measurement is repeated by the number of Retry times, the warning message **"W60**: Retry over!" is displayed and the last measurement result after reduced magnetization is displayed.



As Tolerance becomes small, the measurement time increases, resulting in rising in a sample temperature. Therefore, care should be taken.

■ 6.5 Measurement

• Measurement is made.

START 1 Press

to start measurement and to allow the message "Measuring !"to blink on the screen.

- 2 When the measurement finishes normally, the message "Measuring !"disappears and the measurement result is displayed (see Fig.6-4).
- STOP ③ To forcibly stop measurement after starting the measurement, press result may show *.

. If no measurement is made at that time, the measurement

STOP * Since the time of one cycle becomes long as the measurement frequency becomes low, the time after pressing until the measurement stops actually becomes long.

Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm ³] N1 : 33 Ae : 2.04 [mm ²] We : 1.2 [g] N2 : 33 Mode Select Current Ref. H : 1 :	Excited Conditions Calc. : Normal Function : Frequency : 0.05 [kHz] Hm : 130 [A/m] Tolerance : 1 :
B: V:	Measured Values
	Pcv : 7.6365 [kW/m ³]
500 [mT]/div Fine B	Pcm : 1.0889 [W/kg]
	θ : <u>74.044</u> [deg]
	µa : 6537.3
	Bm : 1058.5 [mT]
	V2m : 8.4970E-02 [V]
	Br : 912.03 [mT]
	Hm : 128.85 [A/m]
	Hc : 35.247 [A/m]
	PC : 1.3067E-03 [W]
	4.7534E-03 [VA]
	0.3275 [A]
	0.8616
	4.3189E-06 [W 0]
	Concernant and Concernat and Concernat and Concernant and Concernant and Concerna
	Configurations
50 [A/m]/div	Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1
IWATELI SY-8219 2015-01-27 10:47:58	Mov-Avg: 3 Pwr Amp: HSA4014-IW Retry: 8

Fig.6-4 Measurement result

■ 6.6 Switching graph

• The displayed graph is switched.

is pressed when the measurement result shown in Fig.6-4 is displayed, the displayed graph changes from B-H graph to the time

axis graph with its horizontal axis used as time shown in Fig.6-5



(1) If

is pressed again, the displayed graph returns to B-H graph.

③ Two time axis graphs are displayed. Waveforms displayed in each graph are shown in Table 6-3.

Graph	Line type	Symbol	Description	* ⁶⁴ Unit
Upper	Thick	В	Magnetic flux density	[mT]/div
side	Thin	Н	Magnetic field strength	[A/m]/div
Lower	Thick	V	Induced voltage	[V]/div
side	Thin	I	Exciting current	[A]/div

Table 6-3 Measurement waveform for time axis graph

* 6-4: Units for time axis graph are fixed: i.e. not changed.



Fig.6-5 Time axis graph

Cross

Grad

Off

Fig.6-6 Cursor menu

■ 6.7 Cursor measurement

■ 6.7.1 Cursor setting

ENTER

∗ If

① Press CURSOR to display the cursor menu shown in Fig.6-6.

② Move the edition cursor to an item to be set and press The cursor being set is displayed.

to determine the setting.

ENTER

is not pressed for approx. 3 seconds, the item on the edition cursor is set automatically.

③ Items to be measured by each cursor are shown in Table 6-4.

Cursor	Display graph	Measurement items		
Cross	B-H	B (magnetic flux density), H (magnetic field strength)		
CIOSS	^{•6-5} Time axis	B, H, V (induced voltage), I (exciting current)		
	B-H	μ (permeability)		
Grad (grade)	*6-5Time axis	B, H, V, I		
Off Cursor not		Cursor not displayed		

Table 6-4 Cursor types and measurement items

* 6-5: Even if Cross or Grad cursor is set for the time axis graph, the cursor is changed to the vertical cursor and the same items can be measured.

■ 6.7.2 Cross cursor measurement (on B-H graph)

- (1) If (i) is rotated when Cross cursor is displayed, Cross cursor moves and the value of the point on the cursor is displayed on Cursor Values.
- 2 Pushing () allows the movement amount of the cursor to toggle between Coarse (movement in unit of 20 points) and

Fine (movement in unit of 1 point). For Fine movement, "Fine" is displayed at the upper side on B-H graph.

Fine display	Cursor measurement value
Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] e : 171.11 [mm³] N Ae : 2.04 [mm²] We : 1.2 [g] N Mode Select Current Ref. Cursor Values H : -17.068 B : 776.83	N1: 33 N2: 33 M2: 130 M2: 130 M2: 1 M2:
500 [m T] /div Fine B Cross cursor	Pcv : 7.6365 [kW/m³] Pcm : 1.0889 [W/kg] 0 : 74.044 [deg] ua : 6537.3 Bm : 1058.5 [mT] V2m : 8.4970E-02 [V] Br : 912.03 [mT] Hm : 128.85 [A/m] Hc : 35.247 [A/m] Pc : 1.3067E-03 [W] VA : 4.7534E-03 [VA] Inm : 0.3275 [A] Br/Bm: 0.8616 2 \$\phi\$m : 4.3189E-06 [Wb] :
IWATELI SY-8219 2015-01-27 1	Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8

Fig.6-7 Cross cursor measurement on B-H graph

■ 6.7.3 Grad cursor measurement (on B-H graph)

① If (in the incline value of the cursor (i.e. ratio permeability:

B/(µ0 · H)) is displayed. (B, H: Magnetic flux density and magnetic field strength at the center of cursor rotation, µ0: vacuum permeability)

- ② The rotation center of Grad cursor is the center of Cross cursor. Therefore, if the position of the rotation center of Grad cursor is to be changed, change the cursor to Cross cursor and move the cursor position.
- 3 Pushing allows the movement amount of the cursor to toggle between Coarse (movement in unit of 20 points) and

Fine (movement in unit of 1 point). For Fine movement, "Fine" is displayed at the upper side on B-H graph.

Sample Parameters Sample Name: SAMPLE Le: 83.878 Made 2.04 State 2.04 Current Ref. u: u: 3.447E+4 Stop Based of the state o	Fine not displayed (Coarse)	Cursor measurement value
Sample Parameters Sample Name: SAMPLE Le: 83.878 [mm] V: 171.11 [mm ³] N1: 33 Ae: 2.04 [mm ²] Wei 1.2 [g] N2: 33 Mode Select Cursor Values Imministration U: 3.447E+4 Imministration Imministration 500 [m1] /div B Imministration Imministration 500 [m1] /div B Imministration Imministration 6500 [m1] /div B Imministration Imministration 6500 [m1] /div B Imministration Imministration Imministration Imministration Imministration		/
STD Current Ref. u: 3.447E+4 500 mT]/div B 600 mT]/div B 90 : 7.6365 [k W/m³] 90 : 1.0889 [W/kg] 912.03 [mT] [deg] [mT] 1058.5 [mT] V2m 8.4970E-02 [V] 11m 128.85 [A/m] 11m 128.85 [A/m] 11m 0.3275 [A] 11m 0.3275 [A] 11m 0.8616 [Wb] 20m : : : : : <td>Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm³] N1 : Ae : 2.04 [mm²] We : 1.2 [g] N2 : Mode Select Cursor Values </td> <td>Excited Conditions Function : Frequency : 0.05 [kHz] Hm : 130 [A/m] Tolerance : \pm 1 [%]</td>	Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm ³] N1 : Ae : 2.04 [mm ²] We : 1.2 [g] N2 : Mode Select Cursor Values	Excited Conditions Function : Frequency : 0.05 [kHz] Hm : 130 [A/m] Tolerance : \pm 1 [%]
500 [mT] /div B 6 7.6365 [kW/m³] 9 cw 1.0889 [W/kg] 0 74.044 [deg] 10 8.4970E-02 [V] Bm 1058.5 [mT] V2m 8.4970E-02 [V] Br 912.03 [mT] Hm 128.85 [A/m] Pc 1.3067E-03 [W] VA 4.7534E-03 [VA] Im 0.3275 [A] Br/Bm 0.3616 2 dm 4.3189E-06 [Wb] : : Configurations (Wb] : : Measured Values :	STD	·
500 [mT] /div B 500 [mT] /div B 6 7.6365 [kW/m³] 9 cm 1.0889 [W/kg] 0 6537.3 Bm 1058.5 [mT] V2m 8.4970E-02 [V] Br 912.03 [mT] Hm 128.85 [A/m] Hc 35.247 [A/m] Pc 1.3067E-03 [W] VA 4.7534E-03 [VA] 1m 0.3275 [A] Br /Bm: 0.8616 2 \ph m: 4.3189E-06 [Wb] : : Configurations		Measured values
500 mTJ /div B 9 cm : 1.0889 [W/kg] 0 : 74.044 [deg] 1 : 6537.3 Bm : 1 : 1058.5 [mT] V2m : 8.4970E-02 [V] Br : 912.03 [mT] Hm : 128.85 [A/m] Hc : 35.247 [A/m] Pc : 1.3067E-03 [W] VA : 4.7534E-03 [VA] Inm : 0.3275 [A] Br/Bm: 0.8616 [Wb] : : : . . Mov-Avg : 4.3189E-06 [Wb] : : . . Mov-Avg : . . Mov-Avg : Pwr Amp HsA4014-rW Retry : 8		Pcv : 7.6365 [kW/m ³]
WATELL SY-8219 2015-01-27 10:65:07 Volume 74.044 [deg] Ha 6537.3 Bm 1058.5 [mT] V2m 8.4970E-02 [V] Br 912.03 [mT] Hm 128.85 [A/m] Hc 35.247 [A/m] Pc 1.3067E-03 [W] VA 4.7534E-03 [VA] Inm 0.3275 [A] Br / Bm 0.8616 [Wb] Imm Configurations [Wb] Reverage 16 Pod Type : SY-955 OSC-0UT : × 0.1	500 [mT] /div B	Pcm : 1.0889 [W/kg]
WATEL SY-8219 2015-01-27 10:55:07		
WATEL SY-8219 2015-01-27 10:55:07		Bm : 6537.3
Br : 912.03 [mT] Hm 128.85 [A/m] Hc : 35.247 [A/m] Pc 1.3067E-03 [W] VA : 4.7534E-03 [VA] I1m 0.3275 [A] Br/Bm: 0.8616 2 \$\phi\$ m : 4.3189E-06 [Wb] : : Configurations [Wb] Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1 Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8		Vam : 9 4070E 02 [V]
Hm : 128.85 [A/m] Hc : 35.247 [A/m] Pc : 1.3067E-03 [W] VA : 4.7534E-03 [VA] I1m : 0.3275 [A] Br/Bm: 0.8616 [Wb] : : . 50 [A/m] /div . 50 [A/m] /div . SY-8219 2015-01-27 10:55:07		Br : 912.03 [mT]
Hc : 35.247 [A/m] Pc : 1.3067E-03 [W] VA : 4.7534E-03 [VA] I1m : 0.3275 [A] Br/Bm: 0.8616 [Wb] : : . 50 [A/m] /div . SY-8219 2015-01-27 10:55:07		Hm : 128.85 [A/m]
Pc : 1.3067E-03 [W] VA : 1.3067E-03 [VA] Inm : 0.3275 [A] Br/Bm: 0.8616 2 \$\phi\$m: 0.8616 2 \$\phi\$m: 0.8616 [Wb] : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : Stress : <td></td> <td>Hc : 35.247 [A/m]</td>		Hc : 35.247 [A/m]
WA : 4.7534E-03 [VA] Grad cursor [A] [A] Br/Bm: 0.3275 [A] Br/Bm: 0.8616 [Wb] : 50 [A/m]/div Kerage: 16 Pod Type: SY-955 OSC-OUT: × 0.1 Mov-Avg: 3 Pwr Amp: HSA4014-IW Retry: 8		Pc : 1.3067E-03 [W]
Grad cursor I 1m : 0.3275 [A] Br / Bm: 0.8616 [Wb] 2 \$\phi\$ m : 4.3189E-06 [Wb] :		H VA : 4.7534E-03 [VA]
Grad cursor Br / Bm: 0.8616 2 o m : 4.3189E-06 [Wb] : 50 [A/m] /div Configurations Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1 Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8		I 1m : 0.3275 [A]
20 m : 4.3189E-06 [Wb] : 50 [A/m] /div Configurations Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1 Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8	Grad cursor	Br/Bm: 0.8616
50 [A/m] /div Configurations WATELL SY-8219 2015-01-27 10:55:07		2 o m : 4.3189E-06 [Wb]
Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8	50 [A/m]	Configurations Average: 16 Pod Type: SY-955 OSC-OUT: × 0.1
	IWATELI SY-8219 2015-01-27 10:55:07	7 Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8

Fig.6-8 Grad cursor measurement on B-H graph

■ 6.7.4 Vertical cursor measurement (on time axis graph)

① If the graph display is changed to the time axis graph when Grad or Cross cursor is displayed, the cursor changes to the vertical cursor.

is rotated when the vertical cursor is displayed, the vertical cursor moves and the value of the point on the cursor is

displayed on Cursor Values.

③ Pushing

② If

allows the movement amount of the cursor to toggle between Coarse (movement in unit of 20 points) and

Fine (movement in unit of 1 point). For Fine movement, "Fine" is displayed at the upper side on B-H graph.

Fine displayed Cur	sor measurement value
Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm ³] N1 : 33 Ae : 2.04 [mm ²] We : 1.2 [g] N2 : 33 Mode Select Cursor Values H : -17.068 I : 4.338E-2 STD Image: State of the second s	Excited Conditions Calc. : Normal Function : Frequency : 0.05 [kHz] Hm : 130 [A/m] Tolerance : ± 1 [%] : Measured Values
Fine B 500 [mT] /div Vertical cursor H 50 [A/m] /div	Pcv : 7.6365 [kW/m³] Pcm : 1.0889 [W/kg] 0 : 74.044 [deg] µa : 6537.3 Bm : 1058.5 [mT] V2m : 8.4970E-02 [V] Br : 912.03 [mT] Hm : 128.85 [A/m] Hc : 35.247 [A/m] Pc : 13067E-03 [W]
V 0.05 [V] /div 0.05 [V] /div 0.01 [A] /div 0.01 [A] /div 0.05 [V] /div 0.05 [V] /div 0.05 [V] /div 0.05 [V] /div	VA : 4.7534E-03 [VA] I 1m : 0.3275 [A] Br / Bm: 0.8616 2 \oplum m : 4.3189E-06 [Wb] : : Configurations Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1 Mov-Avg : 3 Pwr Amp : HSA4014-IW Retry : 8

Fig.6-9 Vertical cursor measurement on time axis graph

■ 6.8 Scaling up/down of graph

- B-H graph is scaled.
 - ① Move the Cross cursor to the position to be scaled when displaying Cross cursor *66.(see Fig.6-10).
 - (2) When B scale is to be scaled, move the edition cursor to the B scale List Box; when H scale is to be scaled, to the H scale List Box. And then

	ENTER	
press		

③ When Popup List opens, move the edition cursor to the scale to be set and press

to determine the scale.

ENTER

If a value larger than a current setting is selected, the displayed graph is scaled down, and if a smaller value is selected, the displayed graph is scaled up (see Fig.6-11).

- ④ Scales to be set are shown in Table 6-5. Selection of Reset allows the displayed graph to return the original scale.
 - * 6-6: If Cross cursor is not displayed, the graph is scaled up/ down using the origin of the graph as a center.

Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm ³] N1 : 33 Ae : 2.04 [mm ²] We : 1.2 [g] N2 : 33 Mode Select Cursor Values STD E 776.83	Excited Conditions Function : Frequency : 0.05 [kHz] Hm : 130 [A/m] Tolerance : ± 1 [%] : Measured Values
500 [mT] /div Fine B Center of scaling up/down B scale H H scale	Pcv : 7.6365 [k W/m³] Pcm : 1.0889 [W/kg] 0 : 74.044 [deg] µa : 6537.3 Bm : 1058.5 [mT] V2m : 8.4970E-02 [V] Br : 912.03 [mT] Hm : 128.85 [A/m] Hc : 35.247 [A/m] Pc : 1.3067E-03 [W] VA : 4.7534E-03 [VA] I1m : 0.3275 [A] Br/Bm: 0.8616 [Wb] [Wb] :
IWATELI SY-8219 2015-01-27 10:50:17	Average Its Pod Type SY-955 OSC-OUT X 0.1 Mov-Avg 3 Pwr Amp HSA4014-IW Retry 8

Fig.6-10 Setting of scaling up/ down by Cross cursor

Table 6-5 Selectable scales

Items	Unit	Selectable scales
H scale	[A/m]/div	Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, 1000, 2000, 5000, 10000
B scale	[mT]/div	Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, 1000

Sample Parameters Sample Name : SAMPLE Le : 83.878 [mm] Ve : 171.11 [mm ³] N1 : 33 Ae : 2.04 [mm ²] We : 1.2 [g] N2 : 33 Mode Select Cursor Values H : 170.058	Excited Conditions Function : Frequency : 0.05 $[kHz]$ Hm : 130 $[A/m]$ Tolerance : ± 1 $[\%]$
STD B: 776.92	Measured Values
116.63	Pcv : 7 c2c5 [kW/m3]
200 [mT] /div Fine B	Pcm : 1 0990 [W/kg]
	θ : 74 044 [deg]
Scaled un B-H granh	Ha : 6537.3
	Bm : 1058.5 [mT]
	V ₂ m : 8.4970E-02 [V]
	Br : 912.03 [mT]
	Hm : 128.85 [A/m]
	Hc : 35.247 [A/m]
\sim	Pc : 1.3067E-03 [W]
▲/ / H	VA : 4.7534E-03 [VA]
	I1m : 0.3275 [A]
	Br/Bm: 0.8616
	2 • m : 4.3189E-06 [Wb]
20 [A/m]/div	Average : 16 Pod Type : SY-955 OSC-OUT : × 0.1
	Mov-Avg: 3 Pwr Amp: HSA4014-IW Retry: 8
IWATELI SY-8219 2015-01-27 10:51:10	

Fig.6-11 Scaling up of Fig.6-10

• The time axis graph is scaled up/ down.

ENTER

① Press

to display the time axis graph (see Fig.6-12).

② When B scale is to be scaled, move the edition cursor to the B scale List Box; when H scale is to be scaled, to the H scale List Box; when V scale is to be scaled, to the V scale List Box; or when I scale is to be scaled, to the I scale List Box.

And then press

. The time axis cannot be scaled up/ down.

(3) When Popup List opens, move the edition cursor to the scale to be set and press

to determine the scale.

If a value larger than a current setting is selected, the displayed graph is scaled down, and if a smaller value is selected, the displayed graph is scaled up (see Fig.6-13).

(4) Scales to be set are shown in Table 6-6. Selection of **RESET** allows the **displayed graph to return the original scale**.

Items	Unit	Selectable scales
H scale	[A/m]/div	Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, 1000, 2000, 5000, 10000
B scale	[mT]/div	Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, 1000
Localo		Reset, 1E-6, 2E-6, 5E-6, 10E-6, 20E-6, 50E-6, 100E-6, 200E-6, 500E-6, 0.001, 0.002, 0.005, 0.01, 0.02, 0.05,
i scale	ĮĄjuiv	0.1, 0.2, 0.5, 1, 2, 5
	D. (1/dis.	Reset, 1E-6, 2E-6, 5E-6, 10E-6, 20E-6, 50E-6, 100E-6, 200E-6, 500E-6, 0.001, 0.002, 0.005, 0.01, 0.02, 0.05,
v scale	Γνγαίν	0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100

Table 6-6 Selectable scales



Fig.6-12 Time axis graph



Fig.6-13 B and I in Fig.6-12 is scaled down

■ 6.9 Reference function

- Measurement using the reference function is explained. This product can **store one set** of measurement conditions or measurement values; i.e. a waveform which has been measured under the other measurement condition can be displayed at the same time, allowing waveform comparison. It is called **Reference function**. Hereinafter, a stored measurement result is called **Reference** (Ref.) and the latest measurement result not stored is called **Current**.
 - $\textcircled{\sc 0}$ When a measurement result is displayed, press

atam unatal 🔿 unlandar

SELECT

STORAGE

to make it Reference.

- 2 Next, change the measurement condition and make another measurement. The measurement result is Current.
- ③ To display Reference, press Low Leach time it is pressed, the measurement condition and value change as shown in Table 6-7. Reference waveform is displayed in light blue and Current waveform in yellow. The status is indicated in Select on the measurement screen (see Fig.6-14 and Fig.6-15).

$[\text{Explanatory note]} \bullet$. display — . not display									
Operation	Display graph		Cursor measure		Meas. condition		Meas. value		
	Current	Ref.	Current	Ref.	Current	Ref.	Current	Ref.	
1	•	-	•	—	•	—		-	
Press once based on ①	-	•	—	•	-	•	—	•	
Press twice based on ①	•	•	•	—	•	—	•	-	
Press 3 times based on $①$	•	•	—	•	—	•	—	•	
Press 4 times based on ①	Same as ①		Same as ①		Same as ①		Same as ①		
Repeated same as above									





Fig.6-14 Reference function in B-H graph



Fig.6-15 Reference function in time axis graph

■ 6.10 USB memory output of screen hardcopy A hardcopy of a measurement screen is generated to USB memory. ① Specify the file format of a screen hardcopy using Print on Utilities screen in advance (see the ■ 5.3 Setting of Print). 2 Insert USB memory into USB port of this product. PRINT 3 When a measurement screen is displayed, press to display Save as screen. (See Fig.6-16.) ENTER (4) Confirm the edition cursor on Target Equipment and press Popup List opens indicating drive of USB memory which is recognized by this product. Move the edition cursor to the drive name to be generated and ENTER press to determine the drive for the output destination. At that time, Save as screen displays the folder and the file on route of the determined USB memory (See Fig.6-17.) * The folder and the file where things except the character that can be input to the name with ten keys are included cannot be displayed. However, only _ (underscore) can be displayed. • If output is made with a new name added on the route Here, how to store F:¥SAMPLE2.jpg is explained. (5) In the status shown in Fig.6-17, move the edition cursor to File Name (see Fig.6-18). ENTER to open Popup Edit Box in which a file name*6-7 6 Press is entered. Use the ten key to enter the file name consisting of alphanumeric characters. To change the input location, press **I I I I** to move the edition cursor. To change a alphanumeric character, press to move the edition cursor to the character and press to change the alphanumeric character. Or, rotate to close Popup Edit Box and determine Finally press the file name

* 6-7: The file name consists of up to 30 characters

including 4 characters for extension.



Fig.6-16 Save As screen

Target Devic	e:	F Drive				
D Application	D EL) Image	D TF	D Meas_Data) patent	D PCT
D POWER AMP	D SY-8218	D temp	D USER DATA	D WORK	ا AMPLE.j	
File Nan	Save					
File Typ	oe:jpeg	file(*.jpg)			Cancel

Fig.6-17 Save As screen



Fig.6-18 Save As screen



Fig.6-19 Save As screen

⑦ Press or rotate (to move the edition cursor to Save button (see Fig6-19), and press



to generate the screen hardcopy with the file name being set (SAMPLE2.jpg) on the route and to close Save as screen.

- * Do not remove USB memory from the USB port during Save operation. A file cannot be generated normally.
- If output is made with a new name added in the existing folder

Here, how to store F:¥Meas_Data¥SAMPLE3.jpg is explained.

⑧ In the status shown in Fig.6-17, move the edition cursor to the file display area (see Fig.6-20).





to Meas_Data folder (see Fig.6-21).

- Press to display the folders and the files in Meas_Data folder (see Fig.6-22).
- Press
 Exit
 to move the edition cursor to the file

display area (see Fig.6-23).

(3) Press 🖵 to move the edition cursor to File Name and

press **ENTER** to open Popup Edit Box to enter the file name.

If the same operation as (6) to (7) is made, the screen hardcopy with the file name being set (SAMPLE3.jpg) is generated in the specified folder and Save as screen is closed (see Fig.6-24).

Save as	
Target Device : F Drive	
Application EL Image ITF Meas_Data patent	PCT
POWER SY-8218 temp USER WORK SAMPLE.j AMP	
File Name :	Save
File Type : jpeg file(*.jpg)	Cancel



Save as						
Target Devi	ce:	F Drive				
D Application		D Image	D TF	D Meas_Data	D patent	D PCT
D POWER AMP	D SY-8218	D temp	D USER DATA	D WORK	⊒ SAMPLE	
File Name :					Save	
File Type : jpeg file(*.jpg)					Cancel	

Fig.6-21 Save As screen

Save as			
Target Device : F Drive			
SAMPLE			
File Name :	Save		
File Type : jpeg file(*.jpg)	Cancel		

Fig.6-22 Save As screen

Save as Target Device : F Drive	Save as Target Device : F Drive
SAMPLE	SAMPLE
File Name : Save	File Name : SAMPLE3.jpg Save
File Type : jpeg file(*.jpg) Cancel	File Type : jpeg file(*.jpg) Cancel

Fig.6-23 Save As screen

• If output is made overwriting the existing file

As shown in Fig.6-25, when the edition cursor moves on the existing file, the file name is displayed on File Name column.

ENTER Press

to move the edition cursor to File Name column.

If the same operation as O is made, Save operation is done so that the existing file is overwritten.

- * At this time, "W68" is displayed. When "Yes" is selected, the superscription is carried out. When "No" are selected, the superscription is canceled.
- If you want to return to upper folder

If you want to return to the upper file when deciding the file output destination, move the edition cursor to the folder showing a file

name using "..." and press as shown in Fig.6-26.

ENTER to return to the upper file,

Fig.6-24 Save As screen



Fig.6-25 Save As screen

Save as Target Device : F Drive	
SAMPLE	
File Name : SAMPLE3.jpg	Save
File Type : jpeg file(*.jpg)	Cancel

Fig.6-26 Save As screen

■ 6.11 Save/ recall of data

• This product can save measurement data and the like in the USB memory as shown in Table6-7. And it can recall the data from the USB memory.

Function	Туре	Objective	File format	Extension	Description
Save	Setup	Only measurement condition	*6-8	.set	Only measurement condition is saved.
(storage)	Data Measurement condition and measurement data Delimited by tab	.mes	The measurement condition and Current ^{*69} waveform measured under that condition are saved.		
	Setup	Only measurement condition		.set	The measurement condition is read out and is set for this product.
Recall (reading out)	Data	Measurement condition and measurement data	Delimited by tab CSV forma	.mes	The measurement condition and measurement data are read out, the measurement conditions set for this product and the measurement data is displayed as Current waveform.

Table 6-8 Save/ recall of data

* 6-8: Never alter the content of the save file. If an altered file is read out resulting in wrong operation or failure, this product shall not be guaranteed and repaired.

- * 6-9: Reference waveform (Storage waveform) cannot be saved. In addition, if a measurement condition is changed and no measurement is made under the changed condition, the measurement data cannot be saved. Only the measurement condition can be saved.
- ① Insert the USB memory into the USB port of this product.



Fig.6-27 Save/Recall selection menu

Save/Recall is displayed. (See Fig.6-27.)

RECALL

2 When

③ Move the edition cursor to a desired function and press

to display selection menu of Setup/Data (see Fig.6-28).

Press of

allows the screen to return to selection menu for Save/Recall.

is pressed while the measurement screen appears, selection menu for

ENTER (4) Move the edition cursor to a desired data type and press

to display the corresponding Save As screen. (See Fig.6-29)

(5) Operation after this step is the same as "
6.10 USB memory output of screen hardcopy."





Fig.6-28 Setup/Data selection menu

Save as	
Target Device : None	
File Name :	Save
File Type : Setup file(*.set)	Cancel

Fig.6-29 Save As screen for Setup

* Never remove the USB memory from the USB port during Save/Recall operation. A file should not be generated normally.

Chapter 7 Troubleshooting and Maintenance

■ 7.1 Error messages and warning messages

• If an error message or a warning message shown in Table 7-1 is displayed on the screen of this product, remedy described in the Table 7-1 should be made.

Displayed messages	Causes	Remedies
E08: Call service!	 Interference of firmware when starting. 	 Restart according to 4.7. When the symptom is the same even if it restarts, contact lwatsu service center to tell the error message No.
E01, E02, E03, E05, E07 , E11 : Call service!	A malfunction occurs in hardware.	• Restart this product. When the symptom is the same even if it restarts, contact lwatsu service center to tell the error message No.
In case of SY-8218, E12 : POD unconnected! Shutdown the SY-8218! In case of SY-8219, E12 : POD unconnected! Shutdown the SY-8219!	 A measurement POD is not connected to this product. The model No. of a measurement POD connected to this product is different from that selected in measurement modes. 	 Power off this product and connect a measurement POD to this product. Power off this product and connect a proper measurement POD. If correspondence Option of Utilities > Option is not Enabled, it is not possible to measure.
E13: Memory bank X data has NaN! E14: Memory bank X shunt resistance errors!	 Non-numerical value is written in memory bank X, or memory bank X is abnormal. The shunt resistance of memory bank X is ≦0. 	Restart this product. When the symptom is the same even if it restarts, contact lwatsu service center to tell the error message No.
E16: SY-821x software version is outdated!	• As the version of the software for the B-H Analyzer is old, it doesn't correspond to SY-810 used.	The main unit software should improve in the version. Contact Iwatsu service center.
E17 : Temp. of FET heat sink on DCS exceeds setting!	• The temperature(thermistor) of the heat sink of SY-961(DCS) exceeded 90°C.	Restart SY-961. When the symptom is the same even if it restarts, contact lwatsu service center to tell the error message No.
E18: DCS over current!	• The output current of SY-961(DCS) exceeded setting value ×1.1.	Power off SY-961. Contact Iwatsu service center to tell the error message No.
W09: Measurement was finished forcibly!	STOP button is pressed to stop measurement forcibly.	_
W12: Temp. of the shunt resistance exceeds setting!	 The temperature of the shunt resistance measuring the exciting current exceeds 80°C. 	 Reduce Hm, Bm, I₁m, and V₂m specified in Fixed Parameter to decrease the exciting current before measurement. Reduce the number of Averages. Or increase Tolerance to make the excitation time short.
W13: Pod cover opens!	POD cover opens.POD is removed from the main unit.	 Close POD cover securely. Power off this product and install POD on the main unit securely.
W14 : Shortage of the exciting current!	 The exciting current is insufficient by approximate value excitation. The DC cable (black) has been disconnected by the DC bias measurement. 	 Confirm whether the sample is connected. Confirm whether the output has gone out of the power amplifier. Raise the gain of the power amplifier. Increase N₁ of the sample. Confirm the disconnection of the DC cable (black).
W15: SST cover opens!	• The cover of SY-956 (SST) is open.	Shut the cover of SY-956 neatly.
W16: DCT cover opens!	• The cover of SY-960 (DCT) is open.	Shut the cover of SY-960 neatly.

Table 7-1 Error / warning messages

Displayed messages	Causes	Remedies
W19: H range over at 1st excitation!	Overflow occurs in the exciting current	• If Hm is specified in Fixed Parameter, confirm that
	measurement range during approximate value excitation.	numeric values and units of Le and $N_1 \mbox{are correct}.$
W20: B range over at 1st excitation!	• Overflow occurs in the induced voltage	• If Bm is specified in Fixed Parameter, confirm that
	measurement range during approximate value excitation.	numeric numbers and units of Ae and N ₂ are correct.
W23: SST serial communication	• Serial communication with SY-956 (SST) is	Restart this product and SY-956.
is abnormal!	abnormal.	When this phenomenon happens frequently,
		message No.
W24: DCT serial communication	Serial communication with SY-960 (DCT) is	Restart this product, SY-960 and SY-961.
is abnormal!	abnormal.	When this phenomenon happens frequently,
		contact lwatsu service center to tell the error
		message No.
w25 : DCS senal communication	Senal communication with SY-961 (DCS) is	Restant this product, SY-960 and SY-961. When this phenomenon happens frequently
is abnormal!	abnormai.	contact lwatsu service center to tell the error
		message No.
W30: Setting condition error! V2 >	• In measurement condition, induced voltage	• Confirm that values and units of N2, Ae, freq. are proper.
200V	exceeds 200[V].	 Confirm that values and units of Bm specified in
		Fixed Parameter is proper.
		Reduce N2 of the sample.
W32: Setting condition error! I1 > 6A	• In measurement condition, exciting current	• Confirm that values and units of N_1 and Le are proper.
	exceeds 6[A].	Confirm that value of Hm specified in Fixed
		Parameter is proper.
		 Increase N1 of the sample.
W34: Setting condition error!	• It is forecast that the output voltage of the third	• Confirm whether the value specified with Fixed
Yoke V3 or V4 > 200V	or fourth turns of the measurement yoke	Parameter is too large.
	exceeds 200V when 2nd is measured by the Single Seat Measurement.	Confirm whether the value of Ae is too large.
W35: Setting condition error!	• It is a measurement condition for the increment	Confirm that values and units of N2, Ae, freq. are proper.
∠VL> 400V	voltage to exceed $400V_{\text{p-p}}$ by the DC bias	 Confirm that values and units of Bm specified in
	measurement.	Fixed Parameter is proper.
		Reduce N2 of the sample.
W36: Setting condition error!	• It is a measurement condition for the increment	• Confirm that values and units of N_1 and Le are proper.
∠lL> 12A	current to exceed $12A_{p,p}$ by the DC bias	Confirm that value of Hm specified in Fixed
	measurement.	Parameter is proper.
		 Increase N1 of the sample.
W41 : OSC output under! \leq 0V	 OSC output is tried to be set under 0V during approximate value excitation. 	 Confirm whether the value specified with Fixed Parameter is too small.
		Reduce the gain of the power amplifier.
W42: Shortage of the exciting current!	• The exciting current is insufficient by asymptote	• Confirm whether the sample is connected or
	excitation.	disconnected.
W43 : OSC output under! \leq 0V	OSC output is tried to be set under 0V during	• Confirm whether the output of the power amplifier
	asymptote excitation.	IS proper.
W50: Measured V2m over	 Induced voltage measured eveneds 200N/I 	 Reduce the gain of the power amplitier. Confirm that values and units of N₂. As and frequencies of N₂.
	\sim in radius voltage in reasoned exceeds 200[v].	are proper.
- 2007		 Confirm that value and unit of Bm specified in Fixed Parameter are proper.
		• Reduce N ₂ of the sample.

Table 7-1 Error/ warning messages

Displayed messages	Causes	Remedies
W51: Measured V2m under!	• Induced voltage measured becomes 0[V] or	Confirm whether the output of the power amplifier
\leq 0V	less.	exceeds ratings.
		Confirm whether secondary turns has been
		disconnected.
W52: Measured I1m over! > 6A	 Exciting current measured exceeds 6[A]. 	\bullet Confirm that values and units of N_1 and Le are
		proper.
		Confirm that value and unit of Hm specified in
		Fixed Parameter are proper.
		• Increase N1 of the sample.
W53 : Measured I1m under! \leq 0A	• Exciting current measured is under 0[A].	Confirm that value and unit of specified in Fixed
		Parameter are proper.
		Contirm that primary turns has not been
		uisconnected.
		this an extremely small current that cannot be measured with this product
W54 [·] Measured VL over!	In DC bias measurement the voltage to be	Confirm the measurement condition
> 2001/	measured exceeds 2001/1	(Refer to section 2.3 of the instruction manual for
2000		SY-960.)
W55: DCS overvoltage!	• The compliance voltage of SY-960 (DCS) is	After confirm whether big Idc is thrown into the
	overvoltage.	sample that ESR is big, restart SY-961.
W56: DCS no current!	• The current is not output from SY-961(DCS).	After confirm whether the DC cable disconnects
		or unconnects, restart SY-961
W57: Temp. of FET heat sink	• The temperature (IC sensor) of the heat sink of	• Restart SY-961.
on DCS exceeds setting!	SY-961(DCS) exceeded 90°C.	When this phenomenon happens frequently,
		contact lwatsu service center to tell the error
		message No.
W58: Temp. of sample on DCT	 The temperature of the sample exceeded the 	 Review the measurement condition.
exceeds setting !	preset temperature of overheating protection	
	switch by the DC bias measurement while	
	measuring.	
W59: Measured ∠IL over!	• It is a measurement condition for the increment	 Confirm the measurement condition.
> 12A	current to exceed $12A_{pp}$ by the DC bias	(Refer to section 2.3 of the Instruction Manual for
	measurement.	SY-960.)
W60: Retry over!	• In the number of excitation times set in	Try to increase Tolerance.
	Configuration > Retry, a measured value of the	• Enlarge the value specified with Fixed
	parameter specified in Fixed Parameter cannot	Parameter.
	be obtained within Tolerance.	Increase the number of Retry times.
		• If B-H curve becomes nearly saturated, change
		Fixed Parameter from Bm to Hm.
W61: Accuracy limit of measurement!	• The minimum limit of core loss measured by	Confirm broken winding and winding applied to
	this product is exceeded.	the measurement POD.
		• Extremely small core loss that cannot be
	—	measured with this product
Especially, when NaN or Infis	I he sample that should be measured with 1-coil	Ivieasure with 1-coil method.
	Internod is measured with 2-coll method.	
vvoz: Not measure in this condition!	Aunougn a measurement condition is changed, no measurement is made and data trias to be	• Aller measurement, save the data.
	no measurement is made and data thes to be	
	Javeu.	

Table 7-1 Error/ warning messages

Displayed messages	Causes	Remedies
W63: C drive cannot save!	 Data or setup tries to be saved in C drive. 	 Connect USB memory to this product and save data in it. This product does not disclose C drive to a user.
W65: Target equipment is not found!	No storage equipment to save / recall is found out (removed on the way).	Press the EXT key and then insert USB memory to save / recall data.
		• The data of a different model can not be recalled.
W66: Read only file cannot be saved!	 Data cannot be saved in the read-only file. 	 Specify other than read-only file for a storage file.
W68: Already exits. Do you want to overwrite it?	• Data tries to be overwritten on an existing file.	Select Yes or No.
W69: Failed in a saved!	• Data fails to be saved. (Memory is full or memory is removed during save operation.)	Remove the cause.
W70: Failed in a recalled!	 It failed in the recall of data. (SST that doesn't correspond to the main unit is connected and so on.) 	Remove the cause.
W71: DCS output time out!	• The electric current output time of SY-961(DCS)	Try to increase Tolerance.
	exceeded the time limit.	Decrease the number of Retry times.
i01: B Coil has been changed.	• Because B coil was changed to User by the	Input the value of N2.
Please enter the N2!	Single Seat Measurement, it is urged to input N2.	
i02: B Coil has been changed.	• It is informed that the kind of B coil of the	• Press the EXIT key to continue the measurement.
Press the EXIT key to start!	attachment was changed by the Single Seat Measurement.	

Table 7-1 Error/ warning messages

■ 7.2 Measurement results

• If the result of measurement on this product shows the phenomenon shown in Table 7-2, it may be improved when remedies described in the Table 7-2 are made.

Phenomena	Causes	Remedies
Right/ left or top/ bottom of B-H curve are reversed.	• Wrong wiring of start. / end of the primary/ secondary turns to the measurement POD.	 Make correct wiring; Start of winding to + side, end to - side.
B-H curve is not symmetry.	DC offset is superimposed on the output of the power amplifier.	 Adjustment is made so that offset of the power amplifier is set to 0. Reduce the gain of the power amplifier. Connect the provided AC couple module to the output of the power amplifier. It cannot be used for measurement less than 10[kHz]. When the frequency less than this is necessary, it is possible to measure by using LF AC COUPLER SY-514.
	• OSC cable SY-911 for IE-1125 is not connected though the power amplifier used is IE-1125x.	Connect OSC cable SY-911 for IE-1125.
Under nearly saturated measurement condition of B-H curve, core loss values disperse.	 Measurement is made with Fixed Parameter specifying Bm. (If B-H curve is nearly saturated, reduce Tolerance and specify Bm for Fixed Parameter. In such a way, small amount of difference of Bm measurement values causes core loss values to disperse greatly.) 	Change the measurement mode to specify Hm for Fixed Parameter.
If the number of turns changes, a core loss value changes greatly.	• The inductance of a sample resonates with the input capacitance of this product.	• Reduce the inductance of the sample. Or reduce the measurement frequency. (See ■ 4.4 Winding of a sample.)
The value of the core loss varies by the measurement day though it is the same sample.	• The magnetic characteristic of the sample changes at the temperature.	 Always measure at the same temperature. It is possible to measure with Chamber Scanner System SY-320x/321x.
	The stability of the magnetic characteristic of the sample is bad.	 A change with the lapse of time of the magnetic characteristic is measured, and confirmed. It is possible to measure with Continuous Measurement Function SY-811.
	• The contact of Chamber Scanner System has been worn out.	• Observe the wear-out condition of contact SY-512, and exchange it if necessary.

Table 7-2 Measurement results

■ 7.3 Others

• If the operation on this product shows the phenomenon shown in Table 7-3, it may be improved when remedies described in the Table 7-3 are made.

Table 7-3 Others					
Phenomena	Causes	Remedies			
If this product is started by pressing POWER switch, it stops on the way of BIOS screen; i.e. it cannot start.	USB equipment is connected to USB port.	• This product can not normally start if USB equipment is inserted in the USB port. Remove the USB equipment from the USB port and restart this product.			
Operation cannot be done on the operation panel.	 This product hangs up for some reason. 	 Power off the main power switch on the rear of this product, wait for 15[sec] or more, restart this product. 			

■ 7.4 Cleaning

• To clean dirt on the outer surface of this product and the cover of the measurement POD, gently wipe them with soft cloth moistened with a small quantity of neutral detergent. Never use organic solvent. If used, discoloration or corrosion may occur.

■ 7.5 Calibration

• Long time use may cause the measurement accuracy of this product to fluctuate, depending on use environment or frequency. Calibration at least once a year is recommended. For details, contact lwatsu office or our sales distributors.

Chapter 8 Specifications

■ 8.1 Oscillator output

: Sine wave 10 Hz to 10 MHz (SY-8218), 10 Hz to 1 MHz (SY-8219)
: Square wave (Duty: 50 %, symmetry) 10 Hz to 1 MHz
: ±0.2 % or less
: 2 % or less
: Max. approx. \pm 3.2 V (50 Ω load, 100 kHz)
: Approx. 50 Ω
: 1/1, 1/2, 1/5, 1/10

■ 8.2 Signal detector (SY-951 / SY-955)

Exciting current detector (H-CH)	
Detection resistance	: Approx. 1 Ω
Detection sensitivity (full scale)	: ± 5 mA, ± 10 mA, ± 20 mA, ± 50 mA, ± 100 mA, ± 200 mA, ± 500 mA, ± 1 A, ± 2 A, ± 5 A, ± 10 A
Max. input permissible current	: ±6 A
Induced voltage detector (B CH)	
Detection sensitivity (full scale)	: ± 5 mV, ± 10 mV, ± 20 mV, ± 50 mV, ± 100 mV, ± 200 mV, ± 500 mV, ± 1 V, ± 2 V, ± 5 V,
	± 10 V, ± 20 V, ± 50 V, ± 100 V, ± 200 V
Max. input permissible current	: ±200 V
Input resistance	: Approx. 1 M Ω
Input capacitance	: Approx. 18.5 pF (between S2-S1 terminals)
AD converter	
Sampling rate	: 50 MS/s (Max.)
Resolution	: 16 bit

■ 8.3 Measurement accuracy

Phase	: ±0.15 deg (Typical value, f =100 kHz, 50 mA, 50 mV range or more, at the amplitude of 80 % or more of used range)
Amplitude	: ± 2 % (Typical value, f=1 kHz, 50 mA, 50 mV range or more)
Core loss	: ± 5.6 % (Typical value, estimated value for θ =80 °, f = 100 kHz, 50 mA, 50 mV range or more)

■ 8.4 Measurement

Calculation mode	
Types	: Normal mode, µ mode
Functions	: Functions in each calculation mode are in accordance with table below:

	Normal mode	µ mode	
	With a frequency fixed, up to a setting target value*1,	With a frequency fixed, up to a setting target	
	and when it is reached, make measurement under	value*1, and when it is reached, make	
Function	conditions at that time, and the property value is	measurement under conditions at that time, and	
	calculated by using the 100th high harmonic of the	the property value is calculated by using the	
	measuring frequency.	fundamental wave element of the measuring	
		frequency excluding part.	
	SY-8218 sine wave: 10 Hz to 10 MHz	SY-8218 sine wave: 10 Hz to 10 MHz	
Measurement frequency	SY-8219 sine wave: 10 Hz to 1 MHz	SY-8219 sine wave: 10 Hz to 1 MHz	
	Square wave (Duty50 %, symmetry): 10 Hz to 1 MHz		

* 1 A target value is the range which is obtained by multiplying Hm, I₁m, Bm, or V₂m being set by Tolerance.

Measurement waveform

Exciting current, induced voltage, magnetic field (intensity), magnetic flux density, B-H curve

Characteristics values

They depend on calculation modes and are in accordance with table below. The symbol to which * adheres is calculated from the fundamental wave element.

Calculation	Normal mode			µ mode		
modes	Symbol	Typical unit	Meaning	Symbol	Typical unit	Meaning
	Pcv	[W/m³]	Core loss per volume	Bm	П	Max. magnetic flux density
	Pcm	[W/kg]	Core loss per mass	V ₂ m	M	Max. induced voltage
	θ	[deg]	Phase angle	Hm	[A/m]	Max. magnetic field
	μ _a — Relative per		Relative permeability	l₁m	[A]	Max. exciting current
	Bm	П	Max. magnetic flux density	μ _a		Relative permeability
	V ₂ m	[V]	Max. induced voltage	*L	[H]	Inductance
alues	Br [T] Residual m density		Residual magnetic flux density	*R	[Ω]	Resistance
ant va	Hm	[A/m]	[A/m] Max. magnetic field [A/m] Coercive force		[Ω]	Impedance
reme	Hc	[A/m]			[W]	Core loss
leasu	Pc	[W]	Core loss	* µ′		Complex permeability (real part)
2	VA	[VA]	Apparent power	* µ″		Complex permeability (imaginary part)
	l₁m	[A]	Max. exciting current	*µz	_	Impedance permeability
	Br/Bm Rectangular ratio 2Φm [Wb] Total flux linkage		Rectangular ratio	* 0	[deg]	Phase angle
			Total flux linkage	*Q		Quality coefficient
	—	-	_	*tanδ	-	Loss coefficient
	_	_	_	THD	[dB]	Total harmonic distortion

Reference function

It remembers a measurement condition, a characteristics value, and measurement waveform data (for each time of measurement).

Cursor measurement

Cross, Grad

Graph display

B-t, H-t, V-t, I-t, B-H

Setting items and setting range

They are in accordance with table below:

Category	Setting items			Setting range	
	Le (effective length of magnet	ic path)	any of mm, cm, and m		
	Ae (effective net core area)		any of μ m ² , mm ² , cm ² , and m ²		
	Ve (effective net volume)		any of mm	³ , cm ³ , and m ³	
	We (effective weight)		either of g a	and kg	
	Freq.(measurement frequency	y)	any of Hz, I	kHz, and MHz	
	B (magnetic flux density)		either of m	Tand T	
Unit	Pc (core loss)		either of m	N and W	
	Pcv (core loss per volume)		any of W/m	1 ³ , kW/m ³ , and mW/m ³	
	Pcm (core loss per mass)		any of W/k	g, W/g, and mW/g	
	L (inductance)		any of µH,	mH, and H	
	I1m (exciting current)		either of mA and A		
	V ₂ m (induced voltage)		either of m	/ and V	
	Sound		either of Or	n and Off	
Information	Warning		either of Or	n and Off	
(equipment	Date		2000-01-01	I - 2099-12-31	
information)	Time		00:00:00 - 2	23:59:59	
Print					
(screen print)	File Format		either of jpg	j and png	
/	Average (number of average cycles)		a power of 2 of 2° - 2° (any of 1, 2, 4, 8, 16, 32, and 64)		
	Retry (number of retry cycles		a power of $2^3 - 2^5$ (any of 8, 16, and 32)		
Measuring	Mov-Avg (moving average cycles)		an odd number in 1 to 111		
Method	Coil (method of turns)		either of 1 and 2		
	Fixed Parameter (target parameter)		any of $B_m H_m I_{1m}$ and V_{2m}		
	Power Amp (used power amplifier)		any of IE-1125, IE-1125A, IE-1125B, HSA4014-IW, HSA4052-IW, HSA4101-IW,		
			Other, and Not Used. However, if Other is selected, arbitrary 10 characters can be		
			entered.		
	Power Amp Gain (power amplifier gain)		an integral	number in 1 - 100	
Setting of	Pod (model number of measurement POD		SY-8218 SY-8219	any of SY-951(Standard), SY-32x(Chamber), SY-956(Single Sheet),	
Equipment	selected by measurement mode)			and SY-960(DC Bias)	
	* POD that can be selected depends on the			any of SY-955(Standard), SY-32x (Chamber), SY-956(Single Sheet),	
	installing option.			and SY-960(DC Bias)	
	BW for Pulse (band limitation of pulse waveform)		any of Off,	100 ns, and 200 ns	
	Sample Name		Up to 20 characters		
	Le, Ae, Ve, We		0.001 to 99999		
	N1 (No. of primary turns),		0.1 to 9999.9		
	N2(No. of secondary turns)				
	Function (signal type)		either of Sine and Pulse (however, Pulse not for µ mode)		
Measurement			SY-8218	2 digits for 10 Hz to 10 MHz and 99 Hz or less, upper 3 digits for	
		Sine		100 Hz or more can be set.	
	Frequency		SY-8219	2 digits for 10 Hz to 1 MHz and 99 Hz or less, upper 3 digits for 100	
	(signal frequency)			Hz or more can be set.	
		Pulse		2 digits for 10 Hz to 1 MHz and 99 Hz or less, upper 3 digits for 100 Hz or more	
			can be set.		
	Hm, I₁m, Bm, V₂m		0.001 to 99999		
	Tolerance (measurement permissible error)		0.1 to 100		

Category	Setting items	Setting range
	H[A/m]/div B[mT]/div aph	any of Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, 1000, 2000, 5000 and 10000
Croph		any of Reset, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, 100, 200, 500, and 1000
Graph		any of Reset, 1E-6, 2E-6, 5E-6, 10E-6, 20E-6, 50E-6, 100E-6, 200E-6, 500E-6, 0.001, 0.002, 0.005, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, and 5
	V[V]/div	any of Reset, 1E-6, 2E-6, 5E-6, 10E-6, 20E-6, 50E-6, 100E-6, 200E-6, 500E-6, 0.001, 0.002, 0.005, 0.01, 0.02, 0.05, 0.1, 0.2, 0.5, 1, 2, 5, 10, 20, 50, and 100

■ 8.5 SYNC OUT

	Output level	: Approx. 3.3 V (for 50 Ω termination)
■ 8.6	Display equipment	
	Method Resolution	: 8.4 type TFT-LCD : SVGA 800×600 pixel
■ 8.7	External memory	
	USB memory	: Up to 5 USB2.0 memories, save/ recall of measurement conditions, save/ recall of measurement data, save of screen hard copy
■ 8.8	Power supply	
	Power supply input range Power consumption Standby power consumption	: 100-240 VAC, 50/60 Hz : 130 VA (Max.) : Approx. 15 VA (at 100 V) / approx. 25 VA (at 240 V) (only when main power SW is ON on the rear)
■ 8.9	Mechanical	
	Outside dimensions Mass	: 420(W) ×480(D) ×266(H) (tolerance: ±2 mm, accessories and projection not included) : B-H Analyzer main unit: approx. 12.5 kg (accessories and options not included) : Standard measurement POD: approx. 1.7 kg (options not included)
■ 8.10) Environmental conditions	
	Operation/ specifications guaranteed range Operation guaranteed humidity range Warming up time Storage temperature	 : operation +5 °C to +35 °C specifications 23 °C±5 °C : 85 % RH (+35 °C, non-condensation) : Specification standard uses guaranteed values 30 minutes after powering on. : -20 °C to 60 °C (5 % to 85 %, non-condensation)

■ 8.11 Certification Standards

This instrument meets requirements of EMC Directive 2014/30/EU and Low Voltage Directive 2014/35/EU.

EMC Directive	
Emission	: EN 61326-1: 2013 (Class A)
	: EN 61000-3-2: 2006+A1 :2009+A2 :2009
	: EN 61000-3-3: 2008
Immunity	: EN 61326-1: 2013
Low Voltage Directive	
Safety	: EN 61010-1: 2010 (Third Edition)
Overvoltage category	: II
Pollution degree	:2

■ 8.12 Accessories

Power cord (2.5 m, Un-shielded) Cord strap OSC cable (BNC-SMA 1 m, shielded) Power amplifier cable (BNC-BNC 1.2 m, shielded) AC couple module Instruction manual (CD) POD cover User's guide

■ 8.13 Outside appearance diagram



-LA

Θ.

(93.8)

(13.3)

Œ

Unit: mm

Θ
Chapter 9 Measurement Accuracy of Core Loss

\blacksquare 9.1 Phase angle θ and core loss Pc in distorted wave

• The following describes the relationship between the phase angle θ and the core loss Pc when a primary exciting current i₁ or a secondary induced voltage V₂ is a distorted wave.

If a B-H curve enter a saturated area; i.e. a primary exciting current i_1 or a secondary induced voltage V_2 is a distorted wave, the relationship between the phase angle θ and the core loss Pc is **not necessarily expressed as "When \theta is large, Pc is small" which is used at the time when i_1 and V_2 are the single sine wave and it is proper to consider** that discussion of the core loss Pc using the phase angle θ is used **as a standard**.

Fig.9-1 shows the power vector. If a measured current and a measured voltage are the single sine wave, the phase angle θ can be expressed using the apparent power VA and the Active power (core loss) Pc, as shown in expression (2-14):

$$\theta = \cos^{-1} \left(\frac{P_c}{VA} \right)$$

(2.14): listed again



It apparently shows "When θ is large, Pc is small).

Next, consider the case where a measured current and a measured voltage are distorted wave; not single sine wave. It corresponds to the case where B-H loop enters a saturated area. The fact that the waveform of a current or voltage is distorted means that the wave includes other frequency ingredient than sine wave of a basic frequency. Consider the phase angel θ at that time.

Actually, a limitless number of frequency ingredients are included. However, to simplify the explanation here, assume that only one frequency ingredient in addition to a basic ingredient (hereinafter called "high-harmonic ingredient") is included.

Fig.9-2 is the vector diagram indicating the case where the apparent power of the basic wave is VA and the apparent power of the high harmonic wave is va. Generally, since a magnetic material has a different core loss and permeability in a different frequency from the basic wave, the direction and intensity of va is different from those of VA. The composed vector of va and VA is the apparent power VA of the distorted wave. The diagram apparently shows that the phase angel θ ' at that time is larger than θ only for the basic wave.

Next, see another power vector diagram: i.e. Fig.9-3. The direction and intensity of va in this diagram are different from those in Fig.9-2, and as a result, the phase angle θ' of the composed apparent power VA' is smaller than θ only for the basic wave.

In either case, the core loss Pc increases to Pc' but the increment of the phase angle is different from that only for the basic wave. It is considered that which type is used is determined by whether increment of the reactive power or the core loss only for the basic wave is larger than that for the high harmonic wave. The increment of the reactive power is considered to be controlled by the inductance (i.e. permeability) or capacitance. On the other hand, the increment of the core loss is considered to be controlled by hysteresis loss or eddy current loss.

As described above, if a B-H loop enters the saturated area; i.e, the single sine wave is not used for explanation, it is proper to consider that discussion of the core loss Pc using the phase angel θ is used as a standard.

Fig.9-1 Phase angle of single sine wave



Fig.9-2 Phase angle of non-single sine wave (1)



Fig.9-3 Phase angle of non-single sine wave (2)

\blacksquare 9.2 Relationship between measurement error of core loss Pc and phase angel θ (1)

 The following describes the relationship between the measurement error of the core loss Pc and the phase angle θ when a primary exciting current i₁ and a secondary induced voltage V₂ are a single sine wave.

As described in Section 9.1, if both a primary exciting current i₁ and a secondary induced voltage V₂ are a single sine wave, the fact that a phase angle θ is large is equal to the fact that a core loss Pc is small. As the phase angle θ becomes close to 90°, the measurement accuracy of the core loss Pc becomes worse. Finally, at θ =90°, the measurement accuracy of the **core loss Pc is dispersed and cannot be specified**. This cannot be escaped from the pure mathematical principle.

If both the primary exciting current i_1 and the secondary induced voltage V_2 are a single sine wave, effective values for both are i and V, and the phase angel between them is θ , the core loss Pc is expressed in expression 9.1):

$$P_c = i \cdot V \cdot \cos\theta \tag{9.1}$$

The expression apparently shows that calculation of the core loss Pc includes ① amplitude measurement error of current and voltage and ② phase measurement error between current and voltage. The amplitude measurement error of ① is the same as the measurement error in a general current/voltage instrument. The phase measurement error of ② is the relative phase difference of current or voltage waveform and corresponds to the time gap of the measured waveform.

Here, assume that real effective values of the current and voltage are i and V, the real value of the phase angle of a sample is θ . In addition, if each measurement error is Δi , ΔV , or $\Delta \theta$, the measurement error of the core loss is expressed by expression (9.2):

$$\Delta P_{c} = \frac{(i + \Delta i) \cdot (V + \Delta V) \cdot \cos(\theta + \Delta \theta) - i \cdot V \cdot \cos\theta}{i \cdot V \cdot \cos\theta}$$
$$= \frac{i + \Delta i}{i} \cdot \frac{V + \Delta V}{V} \cdot \frac{\cos(\theta + \Delta \theta)}{\cos\theta} - 1$$
(9.2)

The 1st term indicates the measurement error of the current, the 2nd term indicates that of the voltage, and the 3rd term indicates that of the phase. The core loss measurement error \angle Pc is more controlled by the 3rd term as the phase angle θ is closer to 90°.

Fig.9-4 shows the core loss measurement error when the phase measurement error $\angle \theta$ varies within the range of $\pm 0.4^{\circ}$ at the phase angel of $\theta = 89.0^{\circ} - 89.8^{\circ}$ (amplitude measurement error not included). For example, when the phase angle is $\theta = 89.6^{\circ}$, the core loss measurement error can be 50% when the phase measurement error is 0.2°



Fig.9-4 Phase measurement accuracy and core loss measurement error for single sine wave

It can be easily understood that for the same phase measurement error $\angle \theta$, the core loss measurement error is dispersed closer to ∞ as the real value θ become close to 90°.

Even if both the primary exciting current i₁ and the secondary induced voltage V₂ are the single sine wave, it is very difficult to measure the **core** loss Pc with high accuracy in the higher phase angle area.

\blacksquare 9.3 Relationship between measurement error of core loss Pc and phase angel θ (2)

 The following describes the relationship between the measurement error of the core loss Pc and the phase angle θ when a primary exciting current i₁ or a secondary induced voltage V₂ is the distorted wave; not a single sine wave.

If a primary exciting current i_1 or a secondary induced voltage V_2 is the distorted wave; not a single sine wave, the measurement accuracy of **the core loss PC becomes worse** than described in Section 9.2. This cannot be also escaped from the pure mathematical principle.

When both the primary exciting current i_1 and the secondary induced voltage V_2 are the distorted wave, the effective value of each frequency ingredient is i_n or V_n , and the phase difference between these ingredients is θ_n , the core loss Pc is expressed by expression (9.3).

$$P_c = \sum_{n=1}^{\infty} i_n \cdot V_n \cdot \cos \theta_n \tag{9.3}$$

In this case, the core loss measurement error is the total of each frequency ingredient of the core loss measurement error shown in expression (9.2), which can be estimated easily by Section 9.2 and which becomes worse.

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